

(M, G_d) are also considered. Although there still remain many problems, we had some progress for the definition of the characteristic classes of the elements of $H^2(M, G_t)$ and $H^2(M, G_d)$ ([9]). The results of §§1-3 are constructed by the differential operator d and the group $G=GL(n, C)$ and G can be replaced by $U(n)$ or $SU(n)$. In §4, we give analogous theory replacing d by D , an arbitrary differential operator over M . It is a refinement of the appendix of [6] (cf. [1], [2], [5], [8]).

§1. Non-abelian de Rham theory of dimension 2

1. Let M be a connected paracompact smooth manifold. On M , we consider the following sheaves.

G_t : the sheaf of germs of constant G -valued functions.

G_d : the sheaf of germs of smooth G -valued functions.

\mathfrak{g}^1 : the sheaf of germs of complex (n, n) -matrix valued 1-forms.

\mathcal{M}^1 : the subsheaf of \mathfrak{g}^1 consisting of forms θ such that $d\theta + \theta \wedge \theta = 0$.

\mathcal{M}^2 : the image sheaf of \mathfrak{g}^1 by the map d^e defined by $d^e\varphi = d\varphi + \varphi \wedge \varphi$.

Using 2-dimensional non-abelian Poincaré lemma, we can give an intrinsic definition of \mathcal{M}^2 . But in this paper, we use this old definition.

Note 1. If G is a Lie group with the Lie algebra \mathfrak{g} such that the exponential map is onto. Then we can define the similar sheaves for G -valued functions and \mathfrak{g} -valued forms.

Note 2. We denote $G_\omega, \mathcal{M}^1_\omega, etc.$, the corresponding sheaves for holomorphic maps. The similar notations are used for other categories.

Definition 1. We define the differential operators ρ and d^e respectively by

$$\rho(g) = g^{-1}dg, \quad d^e\varphi = d\varphi + \varphi \wedge \varphi.$$

The induced maps of ρ and d^e on the sheaves G_d and \mathfrak{g}^1 are also denoted by ρ and d^e respectively.

Note. ρ is defined for Lie group valued functions, while d^e is defined for Lie algebra valued forms. This is the reason of the inhomogeneity of notations. For Lie algebra valued functions, d^e is defined by $d^e f = \rho(e^f) = df + \sum_{n=1}^{\infty} ((ad f)^n df)/(n+1)!$ ([8], [9]).

By definitions, we have the following exact sequence of sheaves.

$$\begin{aligned} (1) \quad & 0 \longrightarrow G_t \xrightarrow{i} G_d \xrightarrow{\rho} \mathcal{M}^1 \longrightarrow 0, \\ (2) \quad & 0 \longrightarrow \mathcal{M}^1 \xrightarrow{i} \mathfrak{g}^1 \xrightarrow{d^e} \mathcal{M}^2 \longrightarrow 0. \end{aligned}$$

The 0-dimensional cohomology sets for these sheaves and 1-dimensional cohomology sets for G_t and G_d are known. But we need other 0-dimensional cohom-

ology sets for \mathcal{M}^1 , \mathfrak{g}^1 and \mathcal{M}^2 based on the action of gauge transformations. For these purposes, we take a locally finite open covering $\mathfrak{U} = \{U_i\}$ of M . We write c_i , c_{ij} , etc., the sections on U_i , $U_i \cap U_j$, etc.,

Definition 2. Let $h = \{h_i\}$ be an element of $C^0(\mathfrak{U}, G_d)$. Then we define the actions of h on $C^0(\mathfrak{U}, \mathfrak{g}^1)$ and on $C^0(\mathfrak{U}, \mathcal{M}^2)$ by

$$(3) \quad h(\theta) = h_i(\theta_i - h_i^{-1}dh_i)h_i^{-1}, \quad \theta = \{\theta_i\} \in C^0(\mathfrak{U}, \mathfrak{g}^1),$$

$$(3)' \quad h(\Theta) = h_i(\Theta_i)h_i^{-1}, \quad \Theta = \{\Theta_i\} \in C^0(\mathfrak{U}, \mathcal{M}^2).$$

By definitions, we have

Lemma 1. For the above actions, the followings hold

$$(4) \quad h_1(h_2(\theta)) = (h_1h_2)(\theta), \quad h_1(h_2(\Theta)) = (h_1h_2)(\Theta), \\ e(\theta) = \theta, \quad e(\Theta) = \Theta, \quad e = e_i(x), \text{ the identity valued function.}$$

$$(5) \quad d^e(h(\theta)) = h(d^e\theta).$$

$$(6) \quad h(C^0(\mathfrak{U}, \mathcal{M}^1)) = C^0(\mathfrak{U}, \mathcal{M}^1).$$

2. $h = \{h_i\} \in C^0(\mathfrak{U}, G_d)$ also acts on $(C^1(\mathfrak{U}, G_d))$ by the action

$$(7) \quad h(\xi) = h_i g_{ij} h_j^{-1}, \quad \xi = \{g_{ij}\}.$$

By definition, we have

$$(4)' \quad h_1(h_2(\xi)) = (h_1h_2)(\xi), \quad e(\xi) = \xi.$$

Definition 3. We set

$$C^1_a(\mathfrak{U}, G_d) = \{\{g_{ij}\} \in C^1(\mathfrak{U}, G_d) \mid g_{ii} = e, g_{ij} = g_{ji}^{-1}\}.$$

By definition, we have

$$(6)' \quad h(C^1_a(\mathfrak{U}, G_d)) = C^1_a(\mathfrak{U}, G_d).$$

Definition 4. Let $\xi = \{g_{ij}\}$ be an element of $C^1(\mathfrak{U}, G_d)$ and \mathcal{E} be one of \mathcal{M}^1 , \mathfrak{g}^1 or \mathcal{M}^2 . Then we define the map δ_ξ on $C^0(\mathfrak{U}, \mathcal{E})$ by

$$(8) \quad \delta_\xi(c)_{ij} = c_j - g_{ji}c_i g_{ij}, \quad c = \{c_i\}.$$

By definition, if ξ is in $C^1_a(\mathfrak{U}, G_d)$, we get

$$(8)' \quad \delta_\xi(c)_{ij} = c_j - g_{ji}c_i g_{ij}^{-1} = c_j - g_{ij}(c_i).$$

Note. The image of δ_ξ is not in $C^1(\mathfrak{U}, \mathcal{E})$ in general. For example, if $\xi \in C^1_a(\mathfrak{U}, G_d)$, we have

$$(9) \quad d^e(\delta_\xi(\theta))_{ij} = \delta_\xi(d^e\theta)_{ij} + [\rho(g_{ij}) - \delta_\xi(\theta)_{ij}, g_{ij}^{-1}\theta_i g_{ij}].$$

Here $[\varphi, \psi]$ means $\varphi \wedge \psi - (-1)^{pq} \psi \wedge \varphi$, $p = \deg \varphi$, $q = \deg \psi$.

Hereafter, we denote t_{ijk} or δg_{ijk} the map $g_{ij}g_{jk}g_{ik}^{-1}$.

Lemma 2. (i). If $\delta_\xi(c)=0$, then $\delta_\xi\rho(c)$ is equal to 0 if and only if

$$(10) \quad h_{ij}c_j h_{ji} = c_j, \quad \xi = \{g_{ij}\} \text{ and } \xi' = \{h_{ij}g_{ij}\}.$$

(ii). If $\xi \in C^1_a(\mathfrak{U}, G_d)$ and $\delta_\xi(c)$ is equal to 0, then

$$(11) \quad t_{ijk}^{-1}c_i t_{ijk} = c_i.$$

(iii). If Θ is in $C^0(\mathfrak{U}, \mathcal{M}^2)$ and $\delta_\xi\Theta = 0$, then $\delta_{h(\xi)}(h(\Theta))$ is equal to 0. If θ is in $C^0(\mathfrak{U}, \mathfrak{g}^1)$ and $\delta_\xi(\theta) = 0$, then $\delta_{h(\xi)}(h(\theta))$ is equal to 0 if and only if

$$(12) \quad \delta_\xi(\rho(h)) = 0.$$

(iv). If $\xi = \{g_{ij}\} \in C^1_a(\mathfrak{U}, G_d)$ and $\delta_\xi(\theta) = 0$, then $\delta_\xi(d^e\theta)$ is equal to 0 if and only if

$$(13) \quad [\rho(g_{ij}), \theta_j] = 0.$$

Proof. (i) and (ii) follow from the definitions. Since

$$\delta_{h(\xi)}(h(\Theta))_{ij} = h_j(\delta_\xi(\Theta)_{ij})h_j^{-1},$$

we have the first assertion of (iii). The second assertion follows from $\delta_{h(\xi)}(h(\theta))_{ij} = h_j(\delta_\xi(\theta)_{ij} - \delta_\xi\rho(h)_{ij})h_j^{-1}$. Since $g_{ij}^{-1}\theta_i g_{ij} = \theta_j$ if $\delta_\xi(\theta) = 0$, we have (iv) by (9).

Note. If h satisfies (12) for $\xi \in C^1_a(\mathfrak{U}, G_d)$, then we have

$$-\rho(h_i) \wedge \rho(h_j) = -[\rho(g_{ij}), g_{ij}^{-1}\rho(h_i)g_{ij}] - g_{ij}^{-1}\rho(h_i)g_{ij} \wedge g_{ij}^{-1}\rho(h_i)g_{ij}.$$

Hence we have

$$[\rho(g_{ij}), \rho(h_j)] = 0.$$

By this equality, if $\delta_\xi(d^e\theta) = \delta_{h(\xi)}(h(\theta)) = 0$, then we have $\delta_{h(\xi)}(d^e(h(\theta))) = 0$.

Definition 5. We assume $\xi = \{g_{ij}\} \in C^1_a(\mathfrak{U}, G_d)$. Then we set

$$Z^0_d(\mathfrak{U}, \mathcal{M}^1) = \{\theta \in C^0(\mathfrak{U}, \mathcal{M}^1) \mid \delta_\xi\theta = 0 \text{ for some } \xi \text{ such that } [\rho(g_{ij}), \theta_j] = 0\}.$$

$$Z^0_d(\mathfrak{U}, \mathfrak{g}^1) = \{\theta \in C^0(\mathfrak{U}, \mathfrak{g}^1) \mid \delta_\xi\theta = 0 \text{ for some } \xi \text{ such that } [\rho(g_{ij}), \theta_j] = 0\}.$$

$$Z^0_d(\mathfrak{U}, \mathcal{M}^2) = \{\Theta \in C^0(\mathfrak{U}, \mathcal{M}^2) \mid \delta_\xi\Theta = 0 \text{ for some } \xi \text{ such that } \rho(\xi) = \delta_\xi(\theta), \\ \Theta = d^e\theta, \text{ and } t_{ijk}^{-1}\theta_i t_{ijk} = \theta_i\}.$$

Definition 6. For $\theta \in Z^0_d(\mathfrak{U}, \mathcal{M}^1)$ or $Z^0_d(\mathfrak{U}, \mathfrak{g}^1)$, we call $h \in C^0(\mathfrak{U}, G_d)$ is an admissible action if

$$\delta_\xi(\rho(h)) = 0, \quad \delta_\xi\theta = 0.$$

Definition 7. For $\Theta \in Z^0_d(\mathfrak{U}, \mathcal{M}^2)$, we call h is an admissible action if

$$\delta_\xi\Theta = 0, \quad \rho(h_i) = t_{ijk}^{-1}\rho(h_i)t_{ijk}.$$

Since we have

$$\begin{aligned} \rho(h_1 h_2) &= \rho(h_2) + h_2^{-1} \rho(h_1) h_2, \\ \delta_\xi(\rho(h_1 h_2))_{ij} &= \delta_\xi \rho(h_2)_{ij} + h_{2,j}^{-1} (\delta_{h_2(\xi)} \rho(h_2))_{ij} h_{2,j}, \end{aligned}$$

these actions are well defined.

Definition 8. *The limit sets of $Z^0_d(\mathfrak{U}, \mathcal{M}^1)$, $Z^0_d(\mathfrak{U}, \mathfrak{g}^1)$ and $Z^0_d(\mathfrak{U}, \mathcal{M}^2)$ with respect to the refinement of the covering \mathfrak{U} , are denoted by $Z^0_d(M, \mathcal{M}^1)$, $Z^0_d(M, \mathfrak{g}^1)$ and $Z^0_d(M, \mathcal{M}^2)$ respectively.*

By definitions 6, 7, admissible actions are defined on $Z^0_d(M, \mathcal{M}^1)$, $Z^0_d(M, \mathfrak{g}^1)$ and $Z^0_d(M, \mathcal{M}^2)$.

Definition 9. *The quotient sets of $Z^0_d(M, \mathcal{M}^1)$, $Z^0_d(M, \mathfrak{g}^1)$ and $Z^0_d(M, \mathcal{M}^2)$ by the admissible actions are denoted $H^0_d(M, \mathcal{M}^1)$, $H^0_d(M, \mathfrak{g}^1)$ and $H^0_d(M, \mathcal{M}^2)$. They called the 0-dimensional cohomolgy sets.*

By the definitions and Lemma 2, we have the following exact sequence

$$0 \longrightarrow Z^0_d(M, \mathcal{M}^1) \xrightarrow{i} Z^0_d(M, \mathfrak{g}^1) \xrightarrow{d^e} Z^0_d(M, \mathcal{M}^2).$$

By (5) and Lemma 2, d^e also induces the map $d^e: H^0_d(M, \mathfrak{g}^1) \longrightarrow H^0_d(M, \mathcal{M}^2)$.

3. **Definition 10.** *Let \mathcal{E} be \mathcal{M}^1 or \mathfrak{g}^1 an $\xi \in C^1(\mathfrak{U}, G_d)$. Then we define the map δ_ξ on $C^1(\mathfrak{U}, \mathcal{E})$ by*

$$(14) \quad \delta_\xi(\omega)_{ijk} = \omega_{jk} - \omega_{ik} + g_{kj} \omega_{ij} g_{jk}, \quad \xi = \{g_{ij}\}.$$

Note. In general, $\delta_\xi(C^1(\mathfrak{U}, \mathcal{M}^1))$ is not contained in $C^2(\mathfrak{U}, \mathcal{M}^1)$.

By definition, $\delta_\xi(\delta_\xi \theta)$ is equal to 0 if and only if $g_{ki} \theta_i g_{ik} = g_{kj} g_{ji} \theta_i g_{ij} g_{jk}$ for any i, j, k . If $\xi \in C^1_a(\mathfrak{U}, G_d)$, then

$$(14)' \quad \delta_\xi(\omega)_{ijk} = \omega_{jk} - \omega_{ik} + g_{jk}^{-1} \omega_{ij} g_{jk}.$$

Definition 11. *Let ξ be in $C^1_a(\mathfrak{U}, G_d)$. Then we set*

$$\begin{aligned} Z^1(\mathfrak{U}, \mathcal{M}^1) &= \{\omega \in C^1(\mathfrak{U}, \mathcal{M}^1) \mid \omega = \rho(g_{ij}) \text{ and } \delta_\xi \omega = 0 \text{ for some } \xi = \{g_{ij}\}\}, \\ Z^1(\mathfrak{U}, \mathfrak{g}^1) &= \{\omega \in C^1(\mathfrak{U}, \mathfrak{g}^1) \mid \delta_\xi \omega = 0 \text{ for some } \xi\}. \end{aligned}$$

Definition 12. *The elements ω and ω' of $Z^1(\mathfrak{U}, \mathcal{M}^1)$ are said to be cohomologous and denoted $\omega \sim \omega'$ if there exists $h = h_1 \in C^0(\mathfrak{U}, G_d)$ such that*

$$(15) \quad \begin{aligned} d(h_i t_{ijk} h_i^{-1}) &= 0 \text{ for any } i, j, k, \omega_{ij} = \rho(g_{ij}), \\ \xi = \{g_{ij}\} &\in C^1_a(\mathfrak{U}, G_d) \text{ and } \delta_\xi(\omega) = 0. \end{aligned}$$

$$(16) \quad \omega_{ij}' = h_j(\omega_{ij} - \delta_\xi \rho(h)_{ij}) h_j^{-1}.$$

Note. By (16), we have $\omega_{ij}' = \rho(h_i g_{ij} h_j^{-1})$. This ω' satisfies $\delta_{\xi'}(\omega') = 0$, where $\xi' = \{h_i g_{ij} h_j^{-1}\} \in C^1_a(\mathfrak{U}, G_d)$.

Definition 13. *The elements ω and ω' of $Z^1(\mathfrak{U}, \mathfrak{g}^1)$ are said to be cohomologous and denoted $\omega \sim \omega'$ if there exist $h = \{h_i\} \in C^0(\mathfrak{U}, G_d)$ and $\theta = \{\theta_i\} \in C^0(\mathfrak{U}, \mathfrak{g}^1)$ such that*

$$(15)' \quad t_{ijk}^{-1}\theta_i t_{ijk} = \theta_i, \text{ for any } i, j, k, \delta_\xi \omega = 0, \xi = \{g_{ij}\},$$

$$(16)' \quad \omega_{ij}' = h_j(\omega_{ij} - \delta_\xi(\theta^i_j)h_j^{-1}).$$

Definition 14. $H^1(\mathfrak{U}, \mathcal{M}^1)$ and $H^1(\mathfrak{U}, \mathfrak{g}^1)$ are defined to be the quotient sets of $Z^1(\mathfrak{U}, \mathcal{M}^1)$ and $Z^1(\mathfrak{U}, \mathfrak{g}^1)$ by the cohomology relations.

Note. The sets of coboundaries are given by $B^1(\mathfrak{U}, \mathcal{M}^1) = \{\omega \mid \omega = \delta_\xi(\theta), \theta \in C^0(\mathfrak{U}, \mathcal{M}^1), \omega = \rho(\xi)\}$ and $B^1(\mathfrak{U}, \mathfrak{g}^1) = \{\omega \mid \omega = \delta_\xi(\theta), t_{ijk}^{-1}\theta_i t_{ijk} = \theta_i\}$.

Note. If $\omega \in C^1(\mathfrak{U}, \mathcal{M}^1)$ satisfies $\omega_{jk} - \omega_{ik} + g_{jk}^{-1}\omega_{ij}g_{jk} = 0$, $\omega_{ij} = \rho(g_{ij})$ for some $\{g_{ij}\}$, then we have

(i) $g_{jk}^{-1}\omega_{ij}g_{jk}$ does not depend on the choice of $\{g_{ij}\}$,

(ii) $\omega_{ii} = 0$ and $\omega_{ij} = -g_{ji}\omega_{ji}g_{ji}^{-1}$.

By (ii), we may assume $\omega = \rho(\xi)$, $\xi \in C^1_a(\mathfrak{U}, G_d)$.

Proposition 1. (i) Let $\xi = \{g_{ij}\}$ be in $C^1_a(\mathfrak{U}, G_d)$. Then $\rho(\xi)$ belongs to $Z^1(\mathfrak{U}, \mathcal{M}^1)$ if and only if $t_{ijk} = (\delta_\xi)_{ijk}$ is a constant map for any i, j, k .

(ii) $Z^1(\mathfrak{U}, \mathfrak{g}^1)$ is equal to $B^1(\mathfrak{U}, \mathfrak{g}^1)$.

Proof. Since we have

$$t_{ijk}^{-1}d(t_{ijk}) = g_{ik}(g_{jk}^{-1}\omega_{ij}g_{jk} + \omega_{jk} - \omega_{ik})g_{ik}^{-1},$$

$d(t_{ijk})$ is equal to 0 if $\omega \in Z^1(\mathfrak{U}, \mathcal{M}^1)$. On the other hand, if $d(t_{ijk})$ is equal to 0, $\omega = \rho(\xi)$ satisfies $\delta_\xi \omega = 0$. Hence we have (i).

Since we have $g_{jk}^{-1}g_{ij}^{-1}\omega_{ki}g_{ij}g_{jk} = g_{jk}^{-1}(\omega_{kj} - \omega_{ij})g_{jk} = -\omega_{jk} + (\omega_{ij} - \omega_{ik}) = -\omega_{ik} = g_{ik}^{-1}\omega_{ki}g_{ik}$ if $\delta_\xi \omega = 0$, we get $t_{ijk}^{-1}\omega_{ki}t_{ijk} = \omega_{ki}$ if $\delta_\xi \omega = 0$. Hence to take a smooth partition of unity $\{e_i\}$ subordinate to U ,

$$\theta_i = \sum_{U_k \cap U_i \neq \emptyset} e_k \omega_{ki}$$

satisfies (15)'. Then, since

$$\theta_j - g_{ij}^{-1}\theta_i g_{ij} = \sum_{U_k \cap U_i \cap U_j \neq \emptyset} e_k (\omega_{kj} - g_{ij}^{-1}\omega_{ki}g_{ij}) = \omega_{ij},$$

ω is equal to $\delta_\xi(\theta)$. Therefore we obtain (ii).

Corollary 1. For elements of $Z^1(\mathfrak{U}, \mathcal{M}^1)$, (15)' follows from (15).

Proof. Since t_{ijk} is a constant, we get $h_i^{-1}(d(h_i t_{ijk} h_i^{-1}))h_i = \rho(h_i) t_{ijk} - t_{ijk} \rho(h_i) = 0$. Hence we have Corollary.

Corollary 2. $H^1(\mathfrak{U}, \mathfrak{g}^1)$ is equal to $\{0\}$.

Note. Corollary 2 does not hold in another category. For example, $H^1(\mathfrak{U}, \mathfrak{g}^1_\omega)$ may not be equal to $\{0\}$ (cf. [6], [7], [22]).

Definition 15. We set $C^1_c(\mathfrak{U}, G_d) = \{g_{ij} \in C^1_a(\mathfrak{U}, G_d) \mid \delta g_{ijk} \text{ is a constant for any } i, j, k\}$.

Let $\mathfrak{B} = \{V_j \mid j \in \mathbf{J}\}$ be a refinement of $\mathfrak{U} = \{U_i \mid i \in \mathbf{I}\}$ and $\tau, \tau': \mathbf{J} > \mathbf{I}$ the maps

such that $V_j \subset U_{\tau(i)} \cap U_{\tau'(i)}$. Then $\{h_i\} = \{g_{\tau(i)\tau'(i)}\}$ gives a chain homotopy between τ^* and τ'^* .

Definition 16. We set $H^1(M, \mathcal{M}^1)$ the limit set $\lim \{H^1(\mathfrak{U}, \mathcal{M}^1) | \tau^*\}$.

Note. $H^1(M, \mathfrak{g}^1)$ is defined by the same way. But by Corollary 2 of proposition 1, we have

$$H^1(M, \mathfrak{g}^1) = \{0\}.$$

4. Definition 17. Let $\bar{\Theta}$ and $\bar{\Theta}'$ be elements of $H^0_d(M, \mathcal{M}^2)$. $\bar{\Theta}$ and $\bar{\Theta}'$ are cohomologous if they have representatives $\Theta = \{\Theta_i\}$ and $\Theta' = \{\Theta'_i\}$ such that $\delta_\xi \Theta = 0$, $\delta_\xi \Theta' = 0$, $\Theta_i = d^e \theta_i$, $\Theta'_i = d^e \theta'_i$, $\rho(\xi) = \delta_\xi \theta$, $\rho(\xi') = \delta_\xi \theta'$, $\theta' = \xi = \{g_{ij}\}$ and $\xi' = \{c_{ij} g_{ij}\}$, where c_{ij} is a constant map.

Note. $\rho(\xi) = \delta_\xi \theta$ if and only if $\theta_j - g_{ij}^{-1}(\theta_i) = 0$.

Definition 18. $H^2_{dR}(M, \mathfrak{g})$ is defined as the quotient set of $H^0_d(M, \mathcal{M}^2)$ by the cohomology relation.

Theorem 1. There is a bijection between $H^2_{dR}(M, \mathfrak{g})$ and $H^1(M, \mathcal{M}^1)$.

Proof. We denote $\langle \Theta \rangle$ the class of $\Theta \in Z^0_d(\mathfrak{U}, \mathcal{M}^2)$ in $H^2_{dR}(M, \mathfrak{g})$. Then we $\delta_\xi \Theta = 0$, $\rho(\xi) = \delta_\xi \theta$, $\xi \in C^1_d(\mathfrak{U}, G_d)$ and $\theta \in C^0(\mathfrak{U}, \mathfrak{g}^1)$. Then, since $t_{ijk}^{-1} \theta_i t_{ijk} = \theta_j$, we obtain

$$\delta_\xi(\rho(\xi)) = \delta_\xi(\delta_\xi \theta) = 0.$$

Hence $\rho(\xi)$ belongs to $Z^1(\mathfrak{U}, M^1)$. If Θ' is another representative of $\langle \Theta \rangle$ such that $\delta_\xi \Theta' = 0$, set $\xi' = \{g'_{ij}\}$ and $\xi' = \{g'_{ij}\}$, we have

$$g'_{ij} = h_i c_{ij} g_{ij} h_j^{-1},$$

where c_{ij} is a constant and $\{h_i\}$ is admissible. Then, since $\rho(c_{ij} g_{ij}) = \rho(g_{ij})$, we may assume $g'_{ij} = h_i g_{ij} h_j^{-1}$. Hence we have $\rho(\xi')_{ij} = h_j(\rho(\xi)_{ij} - \delta_\xi \rho(h_{ij}) h_j^{-1})$ and $d(h_i t_{ijk} h_i^{-1}) = 0$. Therefore $\rho(\xi) \sim \rho(\xi')$ and we can define the map $\iota: H^2_{dR}(M, \mathfrak{g}) \rightarrow H^1(M, \mathcal{M}^1)$ by

$$\iota(\langle \Theta \rangle) = \langle \rho(\xi) \rangle: \text{the class of } \rho(\xi) \text{ in } H^1(M, \mathcal{M}^1).$$

Since $\theta_j = \rho(g_{ij}) + g_{ij}^{-1} \theta_i g_{ij}$ if $\rho(\xi) = \delta_\xi(\theta)$, we have $\delta_\xi d^e \theta = 0$ if $\rho(\xi) = \delta_\xi(\theta)$. Hence we have

$$d\theta_j = -\rho(g_{ij}) \wedge \rho(g_{ij}) - \rho(g_{ij}), \quad g_{ij}^{-1} \theta_i g_{ij} + g_{ij}^{-1} d\theta_i g_{ij}.$$

Therefore $d^e \theta_j = g_{ij}^{-1} d^e \theta_i g_{ij}$, that is $\delta_\xi d^e \theta = 0$. Let $\langle \omega \rangle$ be an element of $H^1(M, \mathcal{M}^1)$. Then we set $\omega = \rho(\xi)$, $\xi \in C^1_d(\mathfrak{U}, G_d)$. By Proposition 1, (ii), we can set $\rho(\xi) = \delta_\xi(\theta)$, $\theta \in C^0(\mathfrak{U}, \mathfrak{g}^1)$. Then by the above calculation, $d^e \theta$ belongs to $Z^0_d(\mathfrak{U}, \mathcal{M}^2)$. If $\omega \sim \omega'$, we set $\omega' = \rho(h(\xi))$. Then $h \in C^0(\mathfrak{U}, G_d)$ defines an admissible action of $d^e \theta$. Hence we can define the map $\kappa: H^1(M, \mathcal{M}^1) \rightarrow H^2_{dR}(M, \mathfrak{g})$ by

$$\kappa(\langle \omega \rangle) = \langle d^e \theta \rangle, \quad \omega = \rho(\xi) = \delta_\xi \theta.$$

By the definitions of ι and κ , $\iota\kappa$ is the identity map of $H^2_{dR}(M, \mathfrak{g})$ and $\kappa\iota$ is the identity map of $H^1(M, \mathcal{M}^1)$. Hence we have Theorem.

Note 1. The kernel of the surjection $\delta: H^0_d(M, \mathcal{M}^2) \rightarrow H^1(M, \mathcal{M}^1)$ is given by $d^e(H^0_t(M, \mathfrak{g}^1))$, $H^0_t(M, \mathfrak{g}^1) = \{\langle \theta \rangle \in H^0_d(M, \mathfrak{g}^1) \mid \delta_\xi \theta = 0 \text{ for some } \xi \in C^1_a(\mathfrak{U}, G_t)\}$. Here $C^1_a(\mathfrak{U}, G_t)$ means $C^1(\mathfrak{U}, G_t) \cap C^1_a(\mathfrak{U}, G_d)$.

Note 2. In holomorphic category, $H^1(M, \mathfrak{g}^1_\omega)$ may not be equal to $\{0\}$ and we have the following exact sequence

$$0 \longrightarrow H^0_t(M, \mathcal{M}^1_\omega) \xrightarrow{i^*} H^0_t(M, \mathfrak{g}^1_\omega) \xrightarrow{d^e} H^0_d(M, \mathcal{M}^2_\omega) \longrightarrow H^1(M, \mathcal{M}^1_\omega) \xrightarrow{i^*} H^1(M, \mathfrak{g}^1_\omega)$$

The image $i^*(\langle \omega \rangle)$ of $\langle \omega \rangle \in H^1(M, \mathcal{M}^1_\omega)$ is the obstruction class of $\langle \omega \rangle$ to be in δ image. Especially, if $\omega = \rho^*(\xi)$, $\xi \in H^1(M, G_\omega)$, $i^*\rho^*(\xi)$ is the obstruction class of ξ to have a holomorphic connection.

§2. The cohomology sets $H^2(M, G^t)$ and $H^2(M, G_d)$

5. Definition 19. Let $\xi = \{g_{ij}\}$ be in $C^1_a(\mathfrak{U}, G_d)$. Then we define a map δ_ξ on $C^2(\mathfrak{U}, G_t)$ (resp. on $C^2(\mathfrak{U}, G_d)$) by

$$(17) \quad (\delta_\xi c)_{i_0 i_1 i_2 i_3} = g_{i_0 i_1} c_{i_1 i_2 i_3} g_{i_0 i_1}^{-1} c_{i_0 i_1 i_3} c_{i_0 i_2 i_3}^{-1} c_{i_0 i_1 i_2}^{-1}.$$

By definition, we have

Lemma 3. (i) δ_ξ maps $C^2(\mathfrak{U}, G_d)$ into $C^3(\mathfrak{U}, G_d)$.

(ii) $\delta_\xi c = e$ if and only if

$$(18) \quad c_{i_0 i_1 i_2} c_{i_0 i_2 i_3} = g_{i_0 i_1} c_{i_1 i_2 i_3} g_{i_0 i_1}^{-1} c_{i_0 i_1 i_3}.$$

(ii)' If $c \in C^2(\mathfrak{U}, G_t)$ satisfies $\delta_\xi c = e$, $g_{i_0 i_1} c_{i_1 i_2 i_3} g_{i_0 i_1}^{-1}$ is a constant map.

(iii) If $\delta_\xi c = \delta_\xi$, $c = e$, we get $h_{i_0 i_1} c_{i_1 i_2 i_3} h_{i_0 i_1}^{-1} = c_{i_1 i_2 i_3}$, where $\xi = \{g_{ij}\}$ and $\xi' = \{h_{ij} g_{ij}\}$.

(iii)' If $\delta_\xi c = \delta_\xi$, c , we get $h_{i_0 i_1} g_{i_0 i_1} c_{i_1 i_2 i_3} g_{i_0 i_1}^{-1} h_{i_0 i_1}^{-1} = g_{i_0 i_1} c_{i_1 i_2 i_3} g_{i_0 i_1}^{-1}$, where $\xi = \{g_{ij}\}$ and $\xi' = \{h_{ij} g_{ij}\}$.

(iv) If $c = \delta_\xi$, that is, $c_{i_0 i_1 i_2} = g_{i_0 i_1} g_{i_1 i_2} g_{i_0 i_1}^{-1}$, then $\delta_\xi(\delta_\xi) = e$.

(v) Define the action of $h = \{h_i\} \in C^0(\mathfrak{U}, G_d)$ on $C^2(\mathfrak{U}, G_t)$ (on $C^2(\mathfrak{U}, G_d)$) by $h(c) = h_{i_0} c_{i_0 i_1 i_2} h_{i_0}^{-1}$, we get

$$\delta_{h(\xi)}(h(c)) = h(\delta_\xi(c)), \quad h(a) = h_{i_0} a_{i_0 i_1 i_2} h_{i_0}^{-1}.$$

Example. If $\delta_\xi c = e$ and $\xi = h_i h_j^{-1}$, then $c' = h^{-1}(c)$ satisfies

$$c'_{i_1 i_2 i_3} c'_{i_0 i_1 i_3} c'_{i_0 i_2 i_3}^{-1} c'_{i_0 i_1 i_2} = e.$$

Definition 20. Let c be an element of $C^2(\mathfrak{U}, G_t)$. Then $h \in C^0(\mathfrak{U}, G_d)$ is called c -admissible if $h(c)$ belongs to $C^2(\mathfrak{U}, G_t)$.

Lemma 4. Let $\delta_\xi c = e$, $\xi = \{g_{ij}\}$ and assume $\xi' = \{a_{ij} g_{ij}\}$ is in $C^1_a(\mathfrak{U}, G_d)$. Then

to set

$$(19) \quad c'_{i_0i_1i_2} = a_{i_0i_1}g_{i_0i_1}a_{i_1i_2}g_{i_0i_1}^{-1}c_{i_0i_1i_2}a_{i_0i_2}^{-1},$$

$\xi'c' = e$ if and only if $a = \{a_{ij}\}$ satisfies

$$(20) \quad (g_{i_0i_1}^{-1}\delta c_{i_0i_1i_2})(g_{i_0i_2}a_{i_2i_3}g_{i_0i_2}^{-1}) = (g_{i_1i_2}a_{i_2i_3}g_{i_1i_2}^{-1})g_{i_0i_1}^{-1}c_{i_0i_1i_2}.$$

Proof. By (18), $\delta_{\xi'} c' = e$ if and only if

$$(18)' \quad c'_{i_0i_1i_2}c'_{i_0i_2i_3} = a_{i_0i_1}g_{i_0i_1}c'_{i_1i_2i_3}g_{i_0i_1}^{-1}a_{i_0i_1}^{-1}c'_{i_0i_1i_3}.$$

By (19), we get

$$\begin{aligned} c'_{i_0i_1i_2}c'_{i_0i_2i_3} &= a_{i_0i_1}g_{i_0i_1}a_{i_1i_2}g_{i_0i_1}^{-1}c_{i_0i_1i_2}a_{i_0i_2}^{-1}a_{i_0i_2}g_{i_0i_2}a_{i_2i_3}g_{i_0i_2}^{-1}c_{i_0i_2i_3}a_{i_0i_3}^{-1}, \\ a_{i_0i_1}g_{i_0i_1}c'_{i_1i_2i_3}g_{i_0i_1}^{-1}a_{i_0i_1}^{-1}c'_{i_0i_1i_3} &= a_{i_0i_1}g_{i_0i_1}a_{i_1i_2}g_{i_1i_2}^{-1}a_{i_2i_3}g_{i_1i_2}^{-1}c_{i_1i_2i_3}a_{i_1i_3}^{-1}g_{i_0i_1}^{-1} \\ & a_{i_0i_1}^{-1}a_{i_0i_1}g_{i_0i_1}a_{i_1i_3}g_{i_0i_1}^{-1}c_{i_0i_1i_3}a_{i_0i_3}^{-1}. \end{aligned}$$

Hence (18)' follows from

$$(18)'' \quad g_{i_0i_1}^{-1}c_{i_0i_1i_2}a_{i_2i_3}g_{i_0i_2}^{-1}c_{i_0i_2i_3} = g_{i_1i_2}a_{i_2i_3}g_{i_1i_2}^{-1}c_{i_1i_2i_3}g_{i_0i_1}^{-1}c_{i_0i_1i_3}.$$

But since $g_{i_0}^{-1}c_{i_0i_1i_3} = c_{i_1i_2i_3}^{-1}g_{i_0i_1}^{-1}c_{i_0i_1i_2}c_{i_0i_2i_3}$ by (18), (18)'' holds if and only if the equality (20) holds. Hence we have Lemma.

Note. If $c = \delta_{\xi}$, (20) always holds. In fact, we get $(g_{i_0i_1}^{-1}c_{i_0i_1i_2})(g_{i_0i_2}a_{i_2i_3}g_{i_0i_2}^{-1}) = (g_{i_1i_2}a_{i_2i_3}g_{i_1i_2}^{-1})(g_{i_0i_1}^{-1}c_{i_0i_1i_2}) = g_{i_1i_2}a_{i_2i_3}g_{i_1i_2}^{-1}$.

6. Definition 21. We set

$$Z^2(\mathfrak{U}, G_t) = \{c \in C^2(\mathfrak{U}, G_t) \mid \delta_{\xi}c = e \text{ for some } \xi \in C^1_c(\mathfrak{U}, G_d)\}.$$

$$Z^2(\mathfrak{U}, G_d) = \{c \in C^2(\mathfrak{U}, G_d) \mid \delta_{\xi}c = e \text{ for some } \xi \in C^1_c(\mathfrak{U}, G_d)\}.$$

Note 1. The definitions of $Z^2(\mathfrak{U}, G_t)$ and $Z^2(\mathfrak{U}, G_d)$ depend on the domain of ξ . From this point of view, the notations $Z^2(\mathfrak{U}, G_t)_{G_d}$ and $Z^2(\mathfrak{U}, G_d)_{G_d}$ are more exact. But we do not use these notations.

Note 2. In [8], we only assume the domain of ξ to be $C^1_d(\mathfrak{U}, G_d)$. But the research on 3-dimensional theory suggests above definitions are more convenient.

Definition 22. $c, c' \in Z^2(\mathfrak{U}, G_t)$ (resp. $Z^2(\mathfrak{U}, G_d)$) are said to be cohomologous and denoted in symbols $c \sim c'$ if there exists $a \in C^1_c(\mathfrak{U}, G_t)$ (resp. $C^1_c(\mathfrak{U}, G_d)$) such that $\xi' = \{a_{ij}g_{ij}\} \in C^1_c(\mathfrak{U}, G_d)$ satisfies (20) for c and c' is expressed by (19). Here $\delta_{\xi}c = e$ and $\xi = \{g_{ij}\}$.

Lemma 5. (i) $c \sim c'$ is an equivalence relation.

(ii) If $c \sim c'$ and $h(a) \in C^1_c(\mathfrak{U}, G_t)$, then $h(c) \sim h(c')$.

Proof. By Lemma 4, if $c \sim c'$ and $c \in Z^2(\mathfrak{U}, G_t)$, c' belongs to $Z^2(\mathfrak{U}, G_t)$. By definition, $c \sim c$. If $c \sim c'$, we get

$$\begin{aligned} c_{i_0i_1i_2} &= g_{i_0i_1}a_{i_1i_2}^{-1}g_{i_0i_1}^{-1}a_{i_0i_1}^{-1}c'_{i_0i_1i_2}a_{i_0i_2} \\ &= a_{i_0i_1}^{-1}(a_{i_0i_1}g_{i_0i_1})a_{i_1i_2}^{-1}(a_{i_0i_1}g_{i_0i_1})^{-1}c'_{i_0i_1i_2}(a_{i_0i_2}^{-1})^{-1}, \end{aligned}$$

$$\begin{aligned}
& ((a_{i_0i_1}g_{i_0i_1})^{-1}c'_{i_0i_1i_2}) ((a_{i_0i_2}g_{i_0i_2})a_{i_2i_3}^{-1}(a_{i_0i_2}g_{i_0i_2})^{-1}) \\
& \quad = a_{i_1i_2}(g_{i_0i_1}^{-1}c_{i_0i_1i_2}g_{i_0i_2}) (a_{i_2i_3}^{-1}g_{i_0i_2}^{-1})a_{i_0i_2}^{-1}, \\
& ((a_{i_1i_2}g_{i_1i_2})a_{i_2i_3}^{-1}(a_{i_1i_2}g_{i_1i_2})^{-1}) ((a_{i_0i_1}g_{i_0i_1})^{-1}c'_{i_0i_1i_2}) \\
& \quad = a_{i_1i_2}(g_{i_1i_2}a_{i_2i_3}^{-1}g_{i_1i_2}^{-1}) (g_{i_0i_1}^{-1}c_{i_0i_1i_2})a_{i_0i_2}^{-1}.
\end{aligned}$$

Hence we have $c' \sim c$. If $c \sim c'$ and $c' \sim c''$, we set

$$c''_{i_0i_1i_2} = b_{i_0i_1}(a_{i_0i_1}g_{i_0i_1})b_{i_1i_2}(a_{i_0i_1}g_{i_0i_1})^{-1}c'_{i_0i_1i_2}b_{i_0i_2}^{-1}.$$

Then we get

$$\begin{aligned}
c''_{i_0i_1i_2} &= b_{i_0i_1}(a_{i_0i_1}g_{i_0i_1})b_{i_1i_2}(a_{i_0i_1}g_{i_0i_1})^{-1}a_{i_0i_1}g_{i_0i_1}^{-1}c_{i_0i_1i_2}a_{i_0i_2}^{-1}b_{i_0i_2}^{-1} \\
& \quad = (b_{i_0i_1}a_{i_0i_1})g_{i_0i_1}(b_{i_1i_2}a_{i_1i_2})g_{i_0i_1}^{-1}c_{i_0i_1i_2}(b_{i_0i_2}a_{i_0i_2})^{-1}.
\end{aligned}$$

On the other hand, since

$$(g'_{i_0i_1}^{-1}c'_{i_0i_1i_2})(g'_{i_0i_2}b_{i_2i_3}g'_{i_0i_2}^{-1}) = (g'_{i_1i_2}b_{i_2i_3}g'_{i_1i_2}^{-1})(g'_{i_0i_1}c'_{i_0i_1i_2}), \quad g'_{ij} = a_{ij}g_{ij},$$

we get

$$a_{i_1i_2}g_{i_0i_1}^{-1}c_{i_0i_1i_2}g_{i_0i_2}b_{i_2i_3}g_{i_0i_2}^{-1}a_{i_0i_2}^{-1} = a_{i_1i_2}g_{i_1i_2}b_{i_2i_3}g_{i_1i_2}^{-1}g_{i_0i_1}^{-1}c_{i_0i_1i_2}a_{i_0i_2}^{-1}.$$

Hence we have

$$(g_{i_0i_1}^{-1}c_{i_0i_1i_2})(g_{i_0i_2}b_{i_2i_3}g_{i_0i_2}^{-1}) = (g_{i_1i_2}b_{i_2i_3}g_{i_1i_2}^{-1})(g_{i_0i_1}^{-1}c_{i_0i_1i_2}).$$

Therefore we obtain

$$\begin{aligned}
& (g_{i_0i_1}^{-1}c_{i_0i_1i_2})(g_{i_0i_2}b_{i_2i_3}a_{i_2i_3}g_{i_0i_2}^{-1}) \\
& \quad = (g_{i_0i_1}^{-1}c_{i_0i_1i_2})(g_{i_0i_2}b_{i_2i_3}g_{i_0i_2}^{-1})(g_{i_0i_2}a_{i_2i_3}g_{i_0i_2}^{-1}) \\
& \quad = (g_{i_1i_2}b_{i_2i_3}g_{i_1i_2}^{-1})(g_{i_0i_1}^{-1}c_{i_0i_1i_2})(g_{i_0i_1}a_{i_2i_3}g_{i_0i_2}^{-1}) \\
& \quad = g_{i_1i_2}b_{i_2i_3}g_{i_1i_2}^{-1}(g_{i_1i_2}a_{i_2i_3}g_{i_1i_2}^{-1})(g_{i_0i_1}^{-1}c_{i_0i_1i_2}) \\
& \quad = (g_{i_1i_2}b_{i_2i_3}g_{i_1i_2}^{-1})(g_{i_0i_1}c_{i_0i_1i_2}).
\end{aligned}$$

Hence $c'' \sim c$. Therefore we have (i). (ii) follows from the following calculation:

$$\begin{aligned}
& (h_{i_0}a_{i_0i_1}h_{i_0}^{-1})(h_{i_0}g_{i_0i_1}h_{i_1}^{-1})(h_{i_1}a_{i_1i_2}h_{i_1}^{-1})(h_{i_0}c_{i_0i_1i_2}h_{i_0}^{-1}). (h_{i_0}a_{i_0i_2}^{-1}h_{i_0}^{-1}) \\
& \quad = h_{i_0}(a_{i_0i_1}g_{i_0i_1}a_{i_1i_2}g_{i_0i_1}^{-1}c_{i_0i_1i_2}a_{i_0i_2}^{-1})h_{i_0}^{-1} \\
& ((h_{i_1}g_{i_1i_0}h_{i_0}^{-1})(h_{i_0}c_{i_0i_1i_2}h_{i_0}^{-1}))((h_{i_0}g_{i_0i_2}h_{i_2}^{-1})(h_{i_2}a_{i_2i_3}h_{i_2}^{-1}). (h_{i_2}g_{i_2i_0}h_{i_0}^{-1})) \\
& \quad = h_{i_1}((g_{i_0i_1}^{-1}c_{i_0i_1i_2})(g_{i_0i_2}a_{i_2i_3}g_{i_0i_2}^{-1}))h_{i_0}^{-1}, \\
& ((h_{i_1}g_{i_1i_2}h_{i_2}^{-1})(h_{i_2}a_{i_2i_3}h_{i_2}^{-1})(h_{i_2}g_{i_2i_1}h_{i_1}^{-1}))((h_{i_1}g_{i_1i_0}h_{i_0}^{-1}). (h_{i_0}c_{i_0i_1i_2}h_{i_0}^{-1})) \\
& \quad = h_{i_1}((g_{i_1i_2}a_{i_2i_3}g_{i_1i_2}^{-1})(g_{i_0i_1}^{-1}c_{i_0i_1i_2}))h_{i_0}^{-1}.
\end{aligned}$$

Definition 23. We denote $H^2(\mathfrak{U}, G_t)$ (resp. $H^2(\mathfrak{U}, G_d)$) the quotient set of $Z^2(\mathfrak{U}, G_t)$ (resp. $Z^2(\mathfrak{U}, G_d)$) by the relation of being cohomologous and admissible actions of the elements of $C^0(\mathfrak{U}, G_d)$.

Let $\mathfrak{B} = \{V_j | j \in \mathbf{J}\}$ be a refinement of $\mathfrak{U} = \{U_i | i \in \mathbf{I}\}$ and let $\tau, \tau': \mathbf{J} \rightarrow \mathbf{I}$ the maps such that $V_j \subset U_{\tau(j)} \wedge U_{\tau'(j)}$. We denote $\tau(j) = i$ and $\tau'(j) = i'$. We set

$$a_{i_0i_1} = c_{i_0i_0'i_1'}c_{i_0i_1i_1'}^{-1}.$$

Then we get

$$\begin{aligned} a_{i_0i_1}g_{i_0i_1}a_{i_1i_2}g_{i_0i_1}^{-1}c_{i_0i_1i_2}a_{i_0i_2}^{-1} \\ = c_{i_0i_0'i_1'}c_{i_0i_1i_1'}^{-1}g_{i_0i_1}c_{i_1i_1'i_2'}c_{i_1i_2i_2'}^{-1}g_{i_0i_1}^{-1}c_{i_0i_1i_2}c_{i_0i_2i_2'}c_{i_0i_0'i_2'}^{-1}. \end{aligned}$$

Since $c \in Z^2(\mathfrak{U}, G_t)$ or $\in Z^2(\mathfrak{U}, G_d)$, we have

$$g_{i_0i_1}^{-1}c_{i_0i_1i_2} = c_{i_1i_2i_2'}g_{i_0i_1}^{-1}c_{i_0i_1i_2'}c_{i_0i_2i_2'}, \quad c_{i_0i_1'i_2'} = c_{i_0i_1i_1'}^{-1}g_{i_0i_1}c_{i_1i_1'i_2'}g_{i_0i_1}^{-1}c_{i_0'i_1i_2'}.$$

Hence we have

$$\begin{aligned} c_{i_0i_0'i_1'}c_{i_0i_1i_1'}^{-1}g_{i_0i_1}c_{i_1i_1'i_2'}c_{i_1i_2i_2'}^{-1}g_{i_0i_1}^{-1}c_{i_0i_1i_2}c_{i_0i_2i_2'}c_{i_0i_0'i_2'}^{-1} \\ = c_{i_0i_0'i_1'}c_{i_0i_1i_1'}^{-1}g_{i_0i_1}c_{i_1i_1'i_2'}g_{i_0i_1}^{-1}c_{i_0i_1i_2'}c_{i_0i_0'i_2'}^{-1} \\ = c_{i_0i_0'i_1'}c_{i_0i_1'i_2'}c_{i_0i_0'i_2'}^{-1}. \end{aligned}$$

There fore we have

$$a_{i_0i_1}g_{i_0i_1}a_{i_1i_2}g_{i_0i_1}^{-1}c_{i_0i_1i_2}a_{i_0i_2}^{-1} = g_{i_0i_0'}c_{i_0'i_1i_2'}g_{i_0i_0'}^{-1}.$$

Since $g = \{g_{ii'}\}$ is c -admissible by Lemma 3 (ii)', this shows $\tau^*(c)$ and $\tau'^*(c)$ give the same element in $H^2(M, G_t)$ (or $H^2(M, G_d)$).

Definition 24. We set $\lim \{H^2(\mathfrak{U}, G_t) | \tau = H^2(M, G_t)\}$ and $\lim \{H^2(\mathfrak{U}, G_d) | \tau = H^2(M, G_d)\}$.

Note. These cohomology sets are not defined absolutely from the sheaves G_t and G_d . Therefore the notations $H^2(M, G_t)_{G_d}$ and $H^2(M, G_d)_{G_d}$ are more exact. But we do not use these notations.

7. Theorem 2. There are maps $\delta = \delta_0 : H^0(M, \mathcal{M}^1) \rightarrow H^1(M, G_t)$ and $\delta = \delta_1 : H^1(M, \mathcal{M}^1) \rightarrow H^2(M, G_t)$ and the following sequence is exact.

$$(21) \quad \begin{array}{ccccccc} 0 & \longrightarrow & H^0(M, G_t) & \xrightarrow{i} & H^0(M, G_d) & \xrightarrow{\rho^*} & H^0(M, \mathcal{M}^1) & \xrightarrow{\delta} & H^1(M, G_t) & \xrightarrow{i^*} & \\ & & & & & & & & & & \\ & & & & & & & & H^1(M, G_d) & \xrightarrow{\rho^*} & H^1(M, \mathcal{M}^1) & \xrightarrow{\delta} & H^2(M, G_t) & \xrightarrow{i^*} & H^2(M, G_d). \end{array}$$

Proof. The exactness of the first six terms of (21) has been known (cf. [3], [15], [21]). δ_0 is defined by

$$(22)_0 \quad \delta_0(\theta) = \{h_U h_V^{-1}\}, \quad h_U^{-1} d h_U = \theta | U, \quad \theta \in H^0(M, \mathcal{M}^1).$$

We define δ_1 by

$$(22)_1 \quad \delta_1(\langle \omega_{ij} \rangle) = \{g_{ij} g_{jk} g_{ik}^{-1}\}, \quad \omega_{ij} = g_{ij}^{-1} d g_{ij}.$$

By Proposition 1, (i) and Lemma 3, (iv), $c_{ijk} = g_{ij} g_{jk} g_{ik}^{-1}$ belongs to $Z^2(\mathfrak{U}, G_t)$. If $\omega_{ij} = \rho(g_{ij}) = \rho(g_{ij}')$, set $g_{ij} = a_{ij} g_{ij}$, a_{ij} is a constant map. We set $c_{ijk}' = g_{ij}' g_{ki}'$. Then we have

$$c_{i_0i_1i_2}' = a_{i_0i_1} g_{i_0i_1} a_{i_1i_2} g_{i_0i_1}^{-1} c_{i_0i_1i_2} a_{i_0i_2}^{-1}.$$

Since (20) holds by the note at the end of Lemma 4, $\{c_{ijk}'\}$ is cohomologous to $\{c_{ijk}\}$. Hence δ_1 is well defined by Lemma 5, (ii). Then we have $\ker \delta_1 = \{\omega_{ij} | \omega_{ij} = \rho(g_{ij}), g_{ij}g_{jk}g_{ki} = e\} = \text{image } \rho^*$. If $i^*(c)$ vanishes, we have

$$c_{ijk} = a_{ij}g_{ij}a_{ik}g_{ij}^{-1}a_{ik}^{-1} = b_{ij}g_{jk}g_{kj}g_{ji}g_{ki}^{-1}b_{ik}^{-1}, \quad b_{ij} = a_{ij}g_{ij}.$$

Hence $\ker i^*$ is contained in $\text{image } \delta$. Since $\text{image } \delta$ is contained in $\ker i^*$ by definition, we have Theorem 2.

Note. If M is a complex manifold, we can define the cohomology sets $H^2(M, G_t)_\omega = H^2(M, G_t)_{G_\omega}$ and $H^2(M, G_\omega) = H^2(M, G_\omega)_{G_\omega}$ by the same way. Then we get the exact sequence

$$\begin{aligned} 0 \longrightarrow H^0(M, G_t) \longrightarrow H^0(M, G_\omega) \longrightarrow H^0(M, \mathcal{M}^1_\omega) \longrightarrow H^1(M, G_t) \longrightarrow H^1(M, G_\omega) \longrightarrow \\ \longrightarrow H^1(M, \mathcal{M}^1_\omega) \longrightarrow H^2(M, G_t)_\omega \longrightarrow H^2(M, G_\omega)_\omega. \end{aligned}$$

Here, $H^2(M, G_t)_\omega$ may differ from $H^2(M, G_t)$.

If $n=1$, that is $G = \mathbf{C}^*$, \mathcal{M}^1 becomes Φ^1 , the sheaf of germs of closed 1-forms over M and we have $H^1(M, \mathcal{M}^1) = H^2(M, \mathbf{C})$, $H^1(M, G_d) = H^2(M, \mathbf{Z})$ and $H^2(M, G_d) = H^3(M, \mathbf{Z})$. The exact sequence (21) is rewritten as the following exact sequence

$$\begin{aligned} 0 \longrightarrow H^0(M, \mathbf{C}^*) \longrightarrow H^0(M, \mathbf{C}^*_d) \longrightarrow H^0(M, \phi^1) \longrightarrow H^1(M, \mathbf{C}^*) \longrightarrow H^2(M, \mathbf{Z}) \longrightarrow \\ \longrightarrow H^2(M, \mathbf{C}) \xrightarrow{\text{exp}^*} H^2(M, \mathbf{C}^*) \longrightarrow H^3(M, \mathbf{Z}). \end{aligned}$$

This comes from the commutativity of the following diagram of sheaves

$$\begin{array}{ccccccc} & & 0 & & 0 & & 0 \\ & & \uparrow & & \downarrow & & \downarrow \\ 0 & \longrightarrow & \mathbf{C}^*_t & \longrightarrow & \mathbf{C}^*_d & \longrightarrow & \mathcal{M}^1 = \phi^1 \longrightarrow 0 \\ & & \uparrow \text{exp} & & \uparrow \text{exp} & & \uparrow d \\ 0 & \longrightarrow & \mathbf{C}_t & \longrightarrow & \mathbf{C}_d & \longrightarrow & \theta^1 \longrightarrow 0 \\ & & \uparrow & & \uparrow & & \uparrow \\ 0 & \longrightarrow & \mathbf{Z} & \longrightarrow & \mathbf{Z} & \longrightarrow & 0 \\ & & \uparrow & & \uparrow & & \\ & & 0 & & 0 & & \end{array}$$

The corresponding diagram for $GL(n, \mathbf{C})$, $n \geq 2$, takes the following form

$$\begin{array}{ccccccc} & & 0 & & 0 & & 0 \\ & & \uparrow & & \uparrow & & \uparrow \\ 0 & \longrightarrow & G_t & \longrightarrow & G_d & \longrightarrow & \mathcal{M}^1 \longrightarrow 0 \\ & & \uparrow \text{exp} & & \uparrow \text{exp} & & \uparrow d^e \\ 0 & \longrightarrow & \mathfrak{g}_{\omega, d} & \longrightarrow & \mathfrak{g}_d & \longrightarrow & \mathcal{M}^1 \longrightarrow 0 \\ & & \uparrow & & \uparrow & & \uparrow \\ 0 & \longrightarrow & N_{,d} & \longrightarrow & N_{,d} & \longrightarrow & 0 \\ & & \uparrow & & \uparrow & & \\ & & 0 & & 0 & & \end{array}$$

Here $\mathfrak{g}_{0,d}$ and $\mathbb{N}_{,d}$ are defined as kernel sheaves of the maps d^e and \exp . Detailed definitions of this diagram and related cohomology sets are given in [9].

8. We denote the natural map from $Z^0_d(M, \mathcal{M}^2)$ onto $H^2_{dR}(M, \mathfrak{g})$ by dR . Then $\delta_c dR$ maps $Z^0_d(M, \mathcal{M}^2)$ into $H^2(M, \mathfrak{G}_t)$. By Theorems 1, 2, we have

Proposition 2. $\Theta = \{\Theta_i\} \in Z^0_d(M, \mathcal{M}^2)$ is realized as a curvature form of a G -bundle over M if and only if $\delta_c dR(\Theta) = 0$.

Corollary. Let $\{M_G, \pi, M\}$ be a principal G -bundle over M and θ a matrix valued 1-form. Then $\Theta \in Z^0_d(M, \mathcal{M}^2)$ can be written as

$$(23) \quad \pi^*(\Theta) = d\theta + \theta \wedge \theta,$$

if and only if $\delta_c dR(\Theta) = 0$. Here M_G depends on Θ .

Proof. If (23) holds, Θ is realized as a curvature form. Hence we have the necessity. If Θ is a curvature form of $\xi = \{g_{ij}\}$ with the associated principal bundle $\{M_G, \pi, M\}$, we have

$$\pi^*(\Theta)|_{\pi^{-1}(U_i)} = h_i^{-1}\theta_i h_i', \quad \pi^*(g_{ij}) = h_i h_j^{-1}.$$

Since Θ is a curvature form, we can set $\Theta_i = d\theta_i' + \theta_i' \wedge \theta_i'$. Then we have θ to set

$$\theta|_{\pi^{-1}(U_i)} = h_i^{-1}(\theta_i' + dh_i h_i^{-1})h_i.$$

Note 1. Usual de Rham groups are the obstructions of global solvabilities of the equations $d\varphi = \phi$, $\deg \phi = 1, 2, \dots$. From this point of view, $H^1(M, \mathcal{M}^1)$ is the obstruction of global solvability of the equation

$$d^e \theta = \Theta, \quad \Theta = \{\Theta_i\}, \quad \theta = \{\theta_i\}, \quad \theta_j = g_{ji}(\theta_i), \quad \Theta_j = g_{ji}(\Theta_i)$$

where $\{g_{ij}\}$ belongs to $C^1_c(U, G_d)$.

Note 2. If $d^e \theta = d^e \theta'$, set $\theta' = \theta + \eta$, η satisfies the equation

$$(24) \quad d\eta + \eta \wedge \eta + [\theta, \eta] = 0.$$

Local solutions of this equation and the relation between gauge transformations are studied in [10] cf. [20].

§3. Characteristic classes for the elements of $H^1(M, \mathcal{M}^1)$.

9. Lemma 6. Let $\Theta = \{\Theta_i\}$ be an element of $Z^0_d(M, \mathcal{M}^2)$. Then $tr(\Theta_{\wedge \dots \wedge \wedge}^p)$ is a closed $2p$ -form on M and its cohomology class is determined by $dR(\Theta)$ for any p .

Proof. Since $\Theta_j = g_{ij}^{-1}\theta_i g_{ij}$, we get $tr(\Theta_{j \wedge \dots \wedge \wedge} \Theta_j) = tr(g_{ij}^{-1}\theta_i \wedge \dots \wedge \theta_i g_{ij}) = tr(\theta_i \wedge \dots \wedge \theta_i)$. Hence $tr(\Theta_{\wedge \dots \wedge \wedge})$ defines a global form on M . Since $\Theta_i = d^e \theta_i$, we have the Bianchi identity $d\Theta = [\Theta, \theta]$. Then, since

$$tr(\Theta_{\wedge \dots \wedge \wedge}^{r-1} \wedge [\theta, \Theta]_{\wedge \dots \wedge \wedge}^{p-r}) = 0,$$

we get

$$d(\text{tr}(\Theta_{\wedge \dots \wedge}^p \Theta)) = \sum_{r=1}^p \text{tr}(\Theta_{\wedge \dots \wedge}^{r-1} \Theta \wedge d\Theta_{\wedge \dots \wedge}^{p-r} \Theta) = 0.$$

Hence $\text{tr}(\Theta_{\wedge \dots \wedge} \Theta)$ is closed. If $\rho(g_{ij}) = \theta_j - g_{ij}^{-1} \theta_i g_{ij} = \theta_j' - g_{ij}^{-1} \theta_i' g_{ij}$, to set $\theta_i' = \theta_i + \eta_i$, we have

$$(25) \quad \theta_j = g_{ij}^{-1} \theta_i g_{ij},$$

$$(25)' \quad d^e(\theta_i') = \theta_i + d\theta_i + \eta_i \wedge \eta_i + [\theta_i, \eta_i].$$

Then, since $\text{tr}(\eta_i \wedge \eta_i) = \text{tr}[\theta_i, \eta_i] = 0$, we get

$$\text{tr}(d^e(\theta_i')_{\wedge \dots \wedge} d^e(\theta_i')) = \text{tr}((\theta_i + d\eta_i)_{\wedge \dots \wedge} (\theta_i + d\eta_i)).$$

By (25), to set $\phi_{i,1} = \theta_i$ and $\phi_{i,-1} = d\eta_i$, we have

$$\text{tr}(\phi_j, \varepsilon_1 \wedge \dots \wedge \phi_j, \varepsilon_p) = \text{tr}(\phi_{i,\varepsilon_1} \wedge \dots \wedge \phi_{i,\varepsilon_p}), \quad \varepsilon_k = \pm 1.$$

Then, since

$$\begin{aligned} & \text{tr}(\Theta_{i \wedge \dots \wedge}^{r-1} \Theta_i \wedge d\eta_i \wedge \phi_{i,\varepsilon_{r+1}} \wedge \dots \wedge \phi_{i,\varepsilon_p}) \\ &= d(\text{tr}(\Theta_{i \wedge \dots \wedge}^{r-1} \Theta_i \wedge \phi_{i,\varepsilon_{r+1}} \wedge \dots \wedge \phi_{i,\varepsilon_p})), \quad r \geq 1, \end{aligned}$$

$\text{tr}(d^e(\theta_i')_{\wedge \dots \wedge} d^e(\theta_i'))$ is cohomologous to $\text{tr}(\Theta_{\wedge \dots \wedge}^p \Theta)$. Hence we have Lemma.

Corollary. *If $\Theta \in Z^0_d(M, \mathcal{M}^2)$, the coefficients of $\det(\mathbf{I} + (t/2\pi\sqrt{-1})\Theta)$ are closed and their de Rham classes are determined by $\iota dr(\Theta)$.*

Definition 25. *Let $\langle \omega \rangle$ be an element of $H^1(M, \mathcal{M}^1)$, Θ an element of $Z^0_d(M, \mathcal{M}^2)$ such that $\iota dR(\Theta) = \langle \omega \rangle$. Then we define the p -th characteristic class $c^p(\langle \omega \rangle)$ of $\langle \omega \rangle$ by*

$$c^p(\langle \omega \rangle) = \langle \varphi_p \rangle, \text{ the de Rham class of } \varphi_p,$$

$$\det\left(\mathbf{I} + \frac{t}{2\pi\sqrt{-1}}\Theta\right) = \mathbf{I} + \varphi_1 t + \dots + \varphi_p t^p + \dots + \varphi_n t^n.$$

Similarly, we define the p -th Chern character of $\langle \omega \rangle$ by

$$\text{ch}(\langle \omega \rangle) = \left(\frac{\sqrt{-1}}{2\pi}\right)^p \frac{1}{p!} \text{rt}(\Theta_{\wedge \dots \wedge}^p \Theta).$$

Proposition 3. (i) $c^p(\langle \omega \rangle)$ and $\text{ch}^p(\langle \omega \rangle)$ are determined by $\langle \omega \rangle$.

(ii) *Let ξ be a G -bundle with the p -th Chern class $c^p(\xi)$ and the p -th Chern character $\text{ch}^p(\xi)$, $i^*: H^{2p}M, \mathbf{Z} \rightarrow H^{2p}(M, \mathbf{C})$ the map induced from the inclusion $i: \mathbf{Z} \rightarrow \mathbf{C}$. Then we have*

$$(26) \quad c^p(\rho^*(\xi)) = i^*(c^p(\xi)),$$

$$(26)' \quad ch^p(\rho^*(\xi)) = ch^p(\xi).$$

(iii) If $\omega = \{\omega_{ij}\}$ and each ω_{ij} is an antihermitian matrix valued 1-form, $c^p(\langle \omega \rangle)$ and $ch^p(\langle \omega \rangle)$ belong to $H^{2p}(M, \mathbf{R})$.

Proof. (i) follows from Lemma 6 and its Corollary. (ii) follows from the theorem of Chern ([12]) and the definition of the Chern character. If ω satisfies the assumption of (iii), there exists an antihermitian matrix valued $\Theta \in Z^0_d(M, \mathcal{M}^2)$ such that $dR(\Theta) = \langle \omega \rangle$. Then, since $\det(\mathbf{I} + (t/2\pi\sqrt{-1})\Theta)$ is a real form coefficients polynomial, we have (iii).

Corollary. $\Theta \in Z^0_d(M, \mathcal{M}^2)$ can not be realized as a curvature form of a G-bundle over M if $c^p(\Theta)$ is not an integral class for some p .

Note. For an element θ of $H^0(M, \mathcal{M}^1)$, we have defined its characteristic class $\beta^p(\theta) \in H^{2p-1}(M, \mathbf{C})$ by

$$\beta^p(\theta) = \text{the de Rham class of } \frac{(-1)^{p-1}}{(2\pi\sqrt{-1})^p} \text{tr } (\theta \wedge \dots \wedge \theta),$$

([6], cf. [27]). The definitions of $\beta^p(\theta)$ and $ch^p(\Theta)$ are parallel. Moreover, $\beta^p(\theta)$ comes from the p -th generator of $H^*(G, \mathbf{Z})$ and $c^p(\Theta)$ comes from the p -th generator of $H^*(BG, \mathbf{Z})$.

10. Example 1. If λ is a complex number, then we have

$$d^e(\lambda\theta) = \lambda d^e\theta + (\lambda^2 - \lambda)\theta \wedge \theta.$$

Hence we have

$$(27)' \quad \text{tr}(d^e(\lambda\theta) \wedge \dots \wedge d^e(\lambda\theta)) = \lambda^p \text{tr}(d^e\theta \wedge \dots \wedge d^e\theta).$$

Therefore, if $\det(\mathbf{I} + (t/2\pi\sqrt{-1})d^e\theta) = \mathbf{I} + \varphi_1 t + \dots + \varphi_n t^n$, we have

$$(27) \quad \det\left(\mathbf{I} + \frac{t}{2\pi\sqrt{-1}} d^e(\lambda\theta)\right) = \mathbf{I} + \lambda\varphi_1 t + \dots + \lambda^p \varphi_p t^p + \dots + \lambda^n \varphi_n t^n.$$

On the other hand, if g is a smooth G-valued function such that

$$(28) \quad (dg)g = g(dg),$$

and g^λ is defined, then

$$(29) \quad \rho(g^\lambda) = \lambda\rho(g).$$

Hence if $\xi = \{g_{ij}\} \in H^1(M, G_d)$ satisfies (28) for any g_{ij} and for a fixed complex number λ , g_{ij}^λ is defined for each i, j , we get

$$\rho(g_{ij}^\lambda) = (\lambda\theta_j) - g_{ij}^{-1}(\lambda\theta_i)g_{ij}, \quad \theta_j - g_{ij}^{-1}\theta_i g_{ij} = \rho(g_{ij}).$$

Therefore, if each θ_i satisfies $g_{ij}^{-\lambda}\theta_i g_{ij} = g_{ij}^{-1}\theta_i g_{ij}$, $\lambda\omega = \{\rho(g_{ij}^\lambda)\}$ belongs to $Z^1(M, \mathcal{M}^1)$. Here $\omega = \{\rho(g_{ij})\}$. Then by (27), we have

$$c^p(\langle \lambda \omega \rangle) = \lambda_p c^p(\langle \omega \rangle).$$

Example 2. Let M be the m -dimensional complex projective space and $\{\mu_1, \dots, \mu_m\}$ an arbitrary set of m complex numbers. We set

$$\omega_{ij} = \begin{pmatrix} \lambda_1 \left(\frac{dz_j}{z_j} - \frac{dz_i}{z_i} \right) & & & \\ & \dots & & 0 \\ & & \dots & \\ & 0 & & \dots \\ & & & \lambda_m \left(\frac{dz_j}{z_j} - \frac{dz_i}{z_i} \right) \end{pmatrix},$$

$$\prod_{i=1}^m (1 + \lambda_i t) = 1 + \mu_1 t + \dots + \mu_m t^m.$$

Then $\omega = \{\omega_{ij}\}$ defines an element $\langle \omega \rangle$ of $H^1(M, \mathcal{M}^1)$ such that

$$c^p(\langle \omega \rangle) = \lambda_p e^p, \quad e^p \text{ is the generator of } H^{2p}(M, \mathbb{Z}).$$

Note. Let $U = U(n)$ be the unitary group, \mathfrak{h} its Lie algebra. Then the sequence $0 \rightarrow U_t \rightarrow U_d \rightarrow \mathcal{M}_{\mathfrak{h}^1} \rightarrow 0$ is exact. Here $\mathcal{M}_{\mathfrak{h}^1}$ is the sheaf of germs of \mathfrak{h} -valued integrable connections. By this sequence, we get the following cohomology exact sequence

$$\begin{aligned} 0 \longrightarrow H^0(M, U_t) \longrightarrow H^0(M, U_d) \longrightarrow H^0(M, \mathcal{M}_{\mathfrak{h}^1}) \longrightarrow H^1(M, U_t) \longrightarrow \\ \longrightarrow H^1(M, U_d) \longrightarrow H^1(M, \mathcal{M}_{\mathfrak{h}^1}) \longrightarrow H^2(M, U_t) \longrightarrow H^2(M, U_d). \end{aligned}$$

In this sequence, we know $H^1(M, G_d) = H^1(M, U_d)$. But example 2 and Proposition 3, (iii) show $H^1(M, \mathcal{M}^1)$ differs from $H^1(M, \mathcal{M}_{\mathfrak{h}^1})$ in general. We also know $H^1(M, G_t)$ differs from $H^1(M, U_t)$. For example, denote σ the generator of $\pi_1(\mathbb{C}^*)$, the representation $\chi_\sigma = \begin{bmatrix} 1 & 2\pi\sqrt{-1} \\ 0 & 1 \end{bmatrix}$ defines an element of $H^1(\mathbb{C}^*, GL(2, \mathbb{C}))$ which is

not in $H^1(\mathbb{C}^*, U(2))$.

11. If $c = c_{ijk}$ belongs to $Z^2(\mathfrak{u}, G_t)$ resp. to $Z^2(\mathfrak{u}, G_d)$, $\det c = \{\det c_{ijk}\}$ belong to $Z^2(\mathfrak{u}, \mathbb{C}^*)$ (resp. to $Z^2(\mathfrak{u}, \mathbb{C}^*_d)$). Since the cohomology class of $\det c$ is determined by the cohomology class of c , we define

$$(30) \quad d^1(\langle c \rangle) = \langle \det c \rangle.$$

By definition, $d^1(\langle c \rangle) \in H^2(M, \mathbb{C}^*)$ (resp. $H^2(M, \mathbb{C}^*_d)$) and we have

$$(31) \quad \exp^*(c^1(\langle \omega \rangle)) = d^1(\delta(\langle \omega \rangle)).$$

To treat higher dimensional characteristic classes for $\langle c \rangle$, we set $a_{i_0 i_1 i_2} = (1/2\pi\sqrt{-1}) \log(c_{i_0 i_1 i_2})$. Then $a = \{a_{i_0 i_1 i_2}\}$ belongs to $C^2(\mathfrak{u}, \mathfrak{g})$. a is not uniquely determined from c . But we can construct appropriate cohomology theory with

coefficients in $\mathfrak{g}_{0,d}$ and \mathfrak{g}_d . To use this theory, if a satisfies

$$(30) \quad \text{tr}(\delta a \cup \dots \cup \delta a) \in Z^{3p}(\mathfrak{u}, \mathbf{Z}),$$

We can define higher order characteristic classes $d^p\langle c \rangle \in H^{3p-1}(M, \mathbf{C}^*)$ and $e^p(c) \in HH^{3p}(M, \mathbf{Z})$, $c \in H^2(M, G_d)$. For details, see [9].

Note. Researches on 3-dimensional theory suggest the possibility of the existence of a matrix valued 3-form (defined relative to gauge and potential) $\Phi = \Phi(c)$ such that

$$i^*(e^p(c)) = \text{the de Rham class of } \text{tr}(\phi_{\wedge \dots \wedge}^p \phi).$$

If this is true, $e^{2p}(c)$ is a torsion class for any p , although it exists as an non zero class.

12. Let Y be a closed subset of M . Then we have the following commutative diagram with exact lines

$$\begin{array}{ccccc} H^1(M, G_d) & \xrightarrow{\rho^*} & H^1(M, \mathcal{M}^1) & \xrightarrow{\delta} & H^2(M, G_t) \\ i_Y \downarrow & & i_Y \downarrow & & i_Y \downarrow \\ H^1(M-Y, G_d) & \xrightarrow{\rho^*} & H^1(M-Y, \mathcal{M}^1) & \xrightarrow{\delta} & H^2(M-Y, G_t). \end{array}$$

Hence we have

Lemma 7. Let $\langle \omega \rangle$ be an element of $H^1(M, \mathcal{M}^1)$. Then $i_Y\langle \omega \rangle$ is in ρ^* -image if and only if $i_Y\delta\langle \omega \rangle$ is equal to 0.

Corollary. Let $\theta \in Z^3_d(M, \mathcal{M}^2)$. On the total space of some G -bundle over $M-Y$, θ is written

$$(23)' \quad \pi^*(\theta) = d\theta + \theta \wedge \theta,$$

if $i_Y\delta dR(\theta) = 0$.

We write r the codimension of Y and assume $r \geq 2$. We also assume M and Y are cooriented and Y is a smooth submanifold (in the case M is a smooth manifold) or a real analytic subvariety in the case M is a real analytic manifold). Then we have the following commutative diagram with exact lines and columns

$$\begin{array}{ccccccc} & & & & H^p(M, \mathbf{Z}) & \xrightarrow{i_Y} & H^p(M-Y, \mathbf{Z}) \\ & & & & \downarrow i^* & & \downarrow i^* \\ \dots & \longrightarrow & R^{p-r}(Y) & \xrightarrow{\delta_Y} & H^p(M, \mathbf{C}) & \xrightarrow{i_Y} & H^p(M-Y, \mathbf{C}) & \xrightarrow{res} & R^{p-r+1}(Y). \\ & & & & \downarrow exp^* & & \downarrow exp^* & & \\ & & & & H^p(M, \mathbf{C}^*) & \xrightarrow{i_Y} & H^p(M-Y, \mathbf{C}^*) & & \end{array}$$

Here $R^p(Y) = H^p(Y, \mathbf{C})$ if Y is topologically non-singular ([4]). By this diagram, we obtain

Lemma 8. *Let c be an element of $H^p(M, \mathbb{C})$. Then $i_Y(c)$ is in i^* -image if and only if $i_Y \exp^*(c) = 0$, and if c is in δ_Y -image, $i_Y \exp^*(c) = 0$.*

By Lemma 8, we have

Proposition 4. *Let $\langle \omega \rangle$ be an element of $H^1(M, \mathcal{M}^1)$ such that $i_Y(\langle \omega \rangle)$ is in ρ^* -image. Then we have*

$$(33) \quad i_Y \exp^*(c^p(\langle \omega \rangle)) = 0, \quad p \geq 1.$$

(33) holds if we have

$$(34) \quad c^p(\langle \omega \rangle) = \delta_Y(\langle \alpha_p \rangle), \quad \langle \alpha_p \rangle \in R^{2p-r}(Y).$$

Corollary. *If $\pi^*(\Theta) = d^e \theta$ on $(M-Y)_{G'}$ the total space of some principal bundle over $M-Y$, then*

$$(33)' \quad i_Y \exp^*(c^p(\Theta)) = 0, \quad p \geq 1.$$

(33)' holds if we have

$$(34)' \quad c^p(\Theta) = \delta_Y(\langle \alpha_p \rangle), \quad \langle \alpha_p \rangle \in R^{2p-r}(Y).$$

Note. we denote $G_d [Y]$ and $\mathcal{M}^1 [Y]$ the sheaves of germs of smooth G -valued functions and integrable connections over M with singularities on Y (cf. [4]). Then we have the following exact sequences of sheaves

$$(35) \quad \begin{array}{ccccccc} 0 & \longrightarrow & G_t & \xrightarrow{i_Y} & G_d [Y] & \longrightarrow & \rho(G_d [Y]) \longrightarrow 0, \\ & & 0 & \longrightarrow & \rho(G_d [Y]) & \longrightarrow & \mathcal{M}^1 [Y] \longrightarrow \text{Res}_{G,Y} \longrightarrow 0. \end{array}$$

The stalk $\text{Res}_{G,Y,x}$ of $\text{Res}_{G,Y}$ at x given by

$$\text{Res}_{G,Y,x} = \lim [\delta(H^0(U(x) - Y, \mathcal{M}^1))].$$

Hence write $\pi_1(U - Y)_x$ the local fundamental group of $U - Y$ at x , $\text{Res}_{G,Y,x}$ is contained in $\text{Hom}(\pi_1(U - Y)_x, G)$ and therefore $\text{Res}_{G,Y} = 0$ if $r \geq 3$.

By (35), we have the following commutative diagram with exact lines

$$\begin{array}{ccccc} H^1(M, G_d) & \xrightarrow{\rho^*} & H^1(M, \mathcal{M}^1) & \xrightarrow{\delta} & H^2(M, G_t) \\ \downarrow i_Y \swarrow \epsilon_Y & & \downarrow i_Y \swarrow \rho^* \swarrow \epsilon_Y & & \downarrow \epsilon_Y \swarrow i_Y \\ H^1(M, G_d[Y]) & \longrightarrow & H^1(M, \rho(G_d [Y])) & \longrightarrow & H^2(M, G_t) \\ \downarrow \nearrow & & \downarrow & & \downarrow \swarrow \\ H^1(M-Y, G_d) & \xrightarrow{\rho^*} & H^1(M-Y, \mathcal{M}^1) & \xrightarrow{\delta} & H^2(M-Y, G_t) \end{array}$$

If Y is smooth and r is even, $H^1(M, G_d [Y]) = H^1(M-Y, G_d)$. In this case, $\epsilon_Y(\langle \omega \rangle)$ is not in ρ^* -image if $\langle \omega \rangle$ is not in ρ^* -image although $i_Y(\langle \omega \rangle)$ is in ρ^* -image. Therefore, if the equivalence of $i_Y(\langle \omega \rangle)$ and an element in ρ^* -image is given by $\{h_i\}$, $\{h_i\}$ is not defined using open covering of $M-Y$ obtained to restrict an open covering of M to $M-Y$. It also suggests $H^1(M, \mathcal{M}^1 [Y])$ may differ from $H^1(M-$

Y, \mathcal{M}^1).

§4. The general case

13. We fix a differential operator $D : C^\infty(M, E) \rightarrow C^\infty(M, F)$, where E, F are complex vector bundles over M . We take a G -vector space H . Then $D_i \otimes 1_H : C^\infty(U_i, E \otimes H) \rightarrow C^\infty(U_i, F \otimes H)$ is a differential operator on U_i . Here $D = \{D_i\}$ and E and F are both trivial on each U_i . By assumption, a smooth G -valued function g on U_i acts on $C^\infty(U_i, E \otimes H)$ and on $C^\infty(U_i, F \otimes H)$. We set

$$\rho_D(g) = g^{-1}(D_i \otimes 1_H)g - D_i \otimes 1_H.$$

If $\rho_D(g) = 0$, g is called a $c(D)$ -class function ([6], [8]). The sheaf of germs of $c(D)$ -class G -valued functions is denoted by $G_{c(D)}$. $\rho_D(G_d)$ is denoted by \mathcal{M}^1_D (in [6], this sheaf was denoted by $L_{G,D}$). By definitions, we have the following exact sequence

$$(1)_D \quad 0 \longrightarrow G_{c(D)} \xrightarrow{i} G_d \xrightarrow{D} \mathcal{M}^1_D \longrightarrow 0.$$

By the definition of ρ_D we have

$$\rho_D(gh) = h^{-1}\rho_D(g)h + \rho_D(g), \quad \rho_D(e) = 0, \quad e = 1_H.$$

Hence we have

$$\rho_D(g_{ij}g_{jk}g_{ik}^{-1}) = g_{ik}(\rho_D(g_{jk}) - \rho_D(g_{ik}) + g_{jk}^{-1}\rho_D(g_{ij})g_{jk})g_{ik}^{-1}.$$

By this formula, we can define the cohomology sets $H^1(M, \mathcal{M}^1_D)$ and $H^2(M, G_{c(D)})$ as follows;

Definitions 11_D and 21_D. We set

$$\begin{aligned} Z^1(\mathfrak{U}, \mathcal{M}^1_D) &= \{ \{\omega_{ij}\} \in C^1(\mathfrak{U}, \mathcal{M}^1_D) \mid \delta_\xi \omega = 0, \omega = \rho_D(\xi), \xi \in C^1_a(\mathfrak{U}, G_d) \}, \\ Z^2(\mathfrak{U}, G_{c(D)}) &= \{ c \in C^2(\mathfrak{U}, G_{c(D)}) \mid \delta_\xi c = 0, \text{ for some } \xi \in C^1_{c(D)}(\mathfrak{U}, G_d) \}. \end{aligned}$$

Here $C^1_{c(D)}(\mathfrak{U}, G_d)$ is $\{ \xi \in C^1_a(\mathfrak{U}, G_d) \mid (\delta_\xi)_{ijk} \text{ is a } c(D)\text{-class function for any } i, j, k \}$.

Definitions 12_D and 22_D. The cohomologous relations on $Z^1(\mathfrak{U}, \mathcal{M}^1_D)$ and on $Z^2(\mathfrak{U}, G_{c(D)})$ are defined as follows:

$$(15)_D \quad \{ \omega_{ij}' \} \sim \{ \omega_{ij} \} \text{ if } \omega_{ij}' = h_j(\omega_{ij} - \rho_D(h_j) + g_{ij}^{-1}\rho_D(h_i)g_{ij})h_j^{-1}, \\ \{ h_i \} \in C^0(\mathfrak{U}, G_d), \quad t_{ijk}\rho_D(h_i)t_{ijk} = \rho_D(h_i),$$

and

$$(19)_D \quad \{ c_{ijk} \} \sim \{ h_i c_{ijk} h_i^{-1} \}, \quad \{ h_i \} \in C^0(\mathfrak{U}, G_d), \\ \{ c_{ijk} \} \sim \{ a_{ij} g_{ij} a_{jk} g_{ij}^{-1} c_{ijk} a_{ik}^{-1} \}, \quad \{ a_{ij} \} \in C^1(\mathfrak{U}, G_{c(D)}).$$

Here $\{ a_{ij} g_{ij} \}$ belongs to $C^1_{c(D)}(\mathfrak{U}, G_d)$ and satisfies the following condition

$$(g_{i_0 i_1}^{-1} c_{i_0 i_1 i_2}) (g_{i_0 i_2} a_{i_2 i_3} g_{i_0 i_2}^{-1}) = (g_{i_1 i_2} a_{i_2 i_3} g_{i_1 i_2}^{-1}) (g_{i_0 i_1}^{-1} c_{i_0 i_1 i_2}).$$

$H^1(M, \mathcal{M}^1_D)$ and $H^2(M, G_{c(D)})$ are defined by these relations. Then we obtain

Theorem 2D. *The following sequence is exact*

$$(21)_D \quad 0 \longrightarrow H^0(M, G_{c(D)}) \xrightarrow{i} H^0(M, G_d) \xrightarrow{\rho_D} H^0(M, \mathcal{M}^1_D) \longrightarrow H^1(M, G_{c(D)}) \xrightarrow{i^*} \\ H^1(M, G_d) \xrightarrow{\rho_D^*} H^1(M, \mathcal{M}^1_D) \longrightarrow H^2(M, G_{c(D)}) \xrightarrow{i^*} H^2(M, G_d).$$

Example. If $D = \bar{\partial}$, $G_{c(D)}$ is the sheaf of germs of holomorphic G -valued functions on M and \mathcal{M}^1_D is the sheaf of germs of matrix valued $(0, 1)$ -forms θ such that $\bar{\partial}\theta + \theta \wedge \theta = 0$ ([18]). If $G = \mathbf{C}^*$, $(21)_D$ reduces to

$$0 \longrightarrow H^0(M, \mathbf{C}^*_\omega) \longrightarrow H^0(M, \mathbf{C}^*_d) \longrightarrow H^0(M, \phi^{0,1}) \longrightarrow H^1(M, \mathbf{C}^*_\omega) \longrightarrow \\ \longrightarrow H^1(M, \mathbf{C}^*_d) \longrightarrow H^1(M, \phi^{0,1}) \longrightarrow H^2(M, \mathbf{C}^*_\omega) \longrightarrow H^2(M, \mathbf{C}^*_d).$$

Here $\phi^{0,1}$ is the sheaf of germs of $\bar{\partial}$ -closed $(0, 1)$ -forms. If M is a compact Kaehler manifold, this sequence is rewritten to

$$0 \longrightarrow H^0(M, \mathbf{C}^*_\omega) \longrightarrow H^0(M, \mathbf{C}^*_d) \longrightarrow H^0(M, \phi^{0,1}) \longrightarrow H^1(M, \mathbf{C}^*_\omega) \longrightarrow \\ \longrightarrow H^2(M, \mathbf{Z}) \longrightarrow H^{0,2}(M, \mathbf{C}) \xrightarrow{exp^*} H^2(M, \mathbf{C}^*_\omega) \longrightarrow H^3(M, \mathbf{Z}).$$

On the other hand, if M is a Stein manifold, $i^*: H^1(M, G_\omega) \rightarrow H^1(M, G_d)$ is a bijection. Hence the sequence $0 \rightarrow H^1(M, \mathcal{M}^1_D) \rightarrow H^2(M, G_\omega) \rightarrow H^2(M, G_d)$ is exact.

14. In this n^o, we assume $E = F$, and the principal symbol $\sigma(D)$ of D does not vanish on any open set of M . We consider a smooth G -valued function g on U to be a linear operator acting on $C^\infty(U, E \otimes H)$. For differential operators $L, L_1, L_2: C^\infty(U, E \otimes H) \rightarrow C^\infty(U, E \otimes H)$, we set

$$L^g = g^{-1}Lg, [L_1, L_2] = L_1L_2 - L_2L_1.$$

Definition 26. *Let U be an open set of M and $L: C^\infty(U, E \otimes H) \rightarrow C^\infty(U, E \otimes H)$ a differential operator of order $k-1$, $k = \text{ord } D$, on U . Then we define a differential operator $D^e(L): C^\infty(U, E \otimes H) \rightarrow C^\infty(U, E \otimes H)$ by*

$$(36) \quad D^e(L) = (D \otimes 1_H + L)^2 - D^2 \otimes 1_H = L^2 + [D \otimes 1_H, L].$$

$D^e(L)$ was denoted by $\rho_D(L)$ in [6]. The following Lemma is also given in [6].

Lemma 9. *D^e has following properties*

$$(37, i) \quad D^e(cL) = cD^e(L) + (c^2 - c)L^2, \quad c \text{ is a constant,}$$

$$(37, ii) \quad D^e(L_1 + L_2) = D^e(L_1) + D^e(L_2) + [L_1, L_2],$$

$$(37, ii)' \quad D^e(L_1 - L_2) = D^e(L_1) - D^e(L_2) - [L_1 - L_2, L_2],$$

$$(37, iii) \quad D^e(L^g) = D^e(L)^g - [\rho_D(g), L^g],$$

$$(37, iv) \quad D^e(\rho_D g) = \rho_D^2(g).$$

Proof. (37, i) and (37, ii) follow from Definition. (37, ii)' follows from (37, i) and (37, ii). Since we have

$$\begin{aligned} D^e(L^g) &= (D \otimes 1_H)L^g + L^g(D \otimes 1_H) + (L^2)^g \\ &= ((D \otimes 1_H)L^g + L^g(D \otimes 1_H) + L^2)^2 + [D \otimes 1_H - (D \otimes 1_H)^g, L^g], \end{aligned}$$

we get (37, iii). (37, iv) follows from Definition.

Corollary 1. *We have*

$$(38) \quad D^e(L^g + \rho_D(g)) = D^e(L)^g + \rho_{D^2}(g).$$

Proof. By (37, ii) and (37, iv), we get

$$D^e(L^g + \rho_D(g)) = D^e(L^g) + \rho_{D^2}(g) + [\rho_D(g), L^g].$$

Hence we have (38) by (37, iii).

Corollary 2. *If $\rho_D(g)$ is $L_2 - L_1^g$, $D^e(L_2)$ is equal to $D^e(L_1)^g + \rho_{D^2}(g)$. Especially, if $D^2=0$, $D^e(L_2)$ is equal to $D^e(L_1)^g$.*

Proof. Set $L_2 = L_1^g + \rho_D(g)$ and apply (38), we have Corollary.

Note. The reason of notational inhomogeneity of ρ_D and D^e was exposed in n°1. For functions, $D^e(f)$ is defined by $\rho_D(e^f)$ (cf. [8]). We also note if f is a g -valued function, we say f to be a $c(D)$ -class function if $f(D \otimes 1_H) = (D \otimes 1_H)f$ (cf [6], [8]).

The next Lemma generalizes gauge transformation

Lemma 10. *Let g be a smooth G -valued function on U and $L : C^\infty(U, E \otimes H) \rightarrow C^\infty(U, E \otimes H)$ a differential operator. We set*

$$(39) \quad g_D(L) = L^{g^{-1}} + \rho_D(g^{-1}) = g(L - \rho_D(g))g^{-1}.$$

Then g_D is a G -action and we have

$$(40) \quad D^e(g_D(L)) = g_{D^2}(D^e(L)).$$

Proof. Since $e_D(L) = L$, to show g_D to be a G -action, we need only to show $g_D(h_D(L)) = (gh)_D(L)$. But this follows from $g(hLh^{-1} - h\rho_D(h)h^{-1})g^{-1} - g\rho_D(g)g^{-1} = (gh)L(gh)^{-1} - gh\rho_D(h)(gh)^{-1} - g\rho_D(g)g^{-1} = (gh)L(gh)^{-1} - gh\rho_D(gh)(gh)^{-1}$. Since g_D is a G -action, (40) follows from (38).

We set $\mathcal{D}_{E \otimes H}^{k-1}$ the sheaf of germs of differential operators $L : C^\infty(U, E \otimes H) \rightarrow C^\infty(U, E \otimes H)$ with the order at most $k-1$. By definition, \mathcal{M}^1_D is a subsheaf of $\mathcal{D}_{E \otimes H}^{k-1}$. D^e induces a sheaf map (also denoted by D^e) on $\mathcal{D}_{E \otimes H}^{k-1}$. Then $\mathcal{M}^1_{D^2}$ is a subsheaf of $D^e(\mathcal{D}_{E \otimes H}^{k-1})$. We set $\mathcal{M}^1_{D^\#} = (D^e)^{-1}(\mathcal{M}^1_{D^2})$. By (37, iv), \mathcal{M}^1_D is a subsheaf of $\mathcal{M}^1_{D^\#}$. If $D^2=0$, $\mathcal{M}^1_{D^\#}$ is the kernel sheaf of D^e . By the actions g_D and g_{D^2} ($\mathcal{D}_{E \otimes H}^{k-1}$ and $D^e \mathcal{D}_{E \otimes H}^{k-1}$) are the G_d -sheaves and D^e is an equivariant map by Lemma 10. Since $\mathcal{M}^1_{D^2}$ is a G_d -subsheaf of $D^e(\mathcal{D}_{E \otimes H}^{k-1})$, $\mathcal{M}^1_{D^\#}$ is a G_d -subsheaf of

$\mathcal{D}_{E \otimes H}^{k-1}$ and \mathcal{M}^1_D is a G_d -subsheaf of $\mathcal{M}^1_D^\#$.

Definition 27. The quotient sheaves of $\mathcal{M}^1_D^\#$, $\mathcal{D}_{E \otimes H}^{k-1}$ and $D^e(\mathcal{D}_{E \otimes H}^{k-1})$ by G_d -actions are denoted by \mathcal{M}^1_D , $\mathcal{D}_{E \otimes H}^{k-1}$, and \mathcal{M}^2_D .

By Definitions, D^e induces the sheaf map $D^e: \mathcal{D}_{E \otimes H}^{k-1} \rightarrow \mathcal{M}^2_D$ and the following sequences are exact

$$(2)_D \quad 0 \longrightarrow \mathcal{M}^1_D \longrightarrow \mathcal{D}_{E \otimes H}^{k-1} \xrightarrow{D^e} \mathcal{M}^2_D \longrightarrow 0,$$

$$(41)_1 \quad 0 \longrightarrow \mathcal{M}^1_D \longrightarrow \mathcal{M}^1_D \longrightarrow \mathcal{M}^1_D \longrightarrow 0,$$

$$(41)_2 \quad 0 \longrightarrow \mathcal{M}^1_{D^2} \longrightarrow D^e(\mathcal{D}_{E \otimes H}^{k-1}) \longrightarrow \mathcal{M}^2_D \longrightarrow 0.$$

Note. If $D^2=0$, $\mathcal{M}^1_{D^2}$ is the 0-sheaf. But \mathcal{M}^2_D may be different from $D^e(\mathcal{D}_{E \otimes H}^{k-1})$ since the G_d -action on $D^e(\mathcal{D}_{E \otimes H}^{k-1})$ may not be trivial unless $n=1$. But the following sequence is exact if $D^2=0$.

$$(2)_{D'} \quad 0 \longrightarrow \mathcal{M}^1_D \longrightarrow \mathcal{D}_{E \otimes H}^{k-1} \xrightarrow{D^e} D^e(\mathcal{D}_{E \otimes H}^{k-1}) \longrightarrow 0.$$

15. If $L \in H^0(M, (\mathcal{D}_{E \otimes H}^{k-1}))$, \bar{L} has a representative $\{L_i\} \in C^0(\mathfrak{U}, (\mathcal{D}_{E \otimes H}^{k-1}))$ such that $L_j = g_{ji,D}(L_i)$, $\{g_{ji}\} \in C^1(\mathfrak{U}, G_d)$. For $\xi = \{g_{ij}\}$, we set $\delta_{\xi,D}(L)_{ij} = L_j - g_{ji,D}(L_i)$.

Definition 28. Let $\xi = \{g_{ij}\}$ be in $C^1_a(\mathfrak{U}, G_d)$. Then we set

$$H^0_d(M, (\mathcal{D}_{E \otimes H}^{k-1})) = \{L \in H^0(M, (\mathcal{D}_{E \otimes H}^{k-1})) \mid L = L_i, \delta_{\xi,D}L = 0 \text{ and } L_i^t{}_{ijk} = L_i \text{ for some } \xi\}$$

D^e induces a map from $H^0(M, (\mathcal{D}_{E \otimes H}^{k-1}))$ into $H^0(M, \mathcal{M}^2_D)$. We set

$$(42) \quad H^0_D(M, \mathcal{M}^2_D) = D^e(H^0_d(M, (\mathcal{D}_{E \otimes H}^{k-1}))).$$

Theorem 1D. There is a surjection $dR_D: H^0_D(M, \mathcal{M}^2_D) \rightarrow H^1(M, \mathcal{M}^1_D)$.

Proof. If $\theta \in H^0_D(M, \mathcal{M}^2_D)$, θ is represented by $\{D^e(L_i), \{L_i\} \in H^0_d(M, (\mathcal{D}_{E \otimes H}^{k-1}))\}$. Hence there exists $\{g_{ij}\} \in C^1_a(\mathfrak{U}, G_d)$ such that to set $\omega_{ij} = L_j - L_i^g{}_{ji} = \rho_D g_{ij}$, we get $\omega_{jk} = \omega_{ik} + \omega_i^g{}_{jk} = 0$. That is, $\{\omega_{ij}\}$ defines an element of $H^1(M, \mathcal{M}^1_D)$. If $\{D^e(L_i')\}$ is another representative of θ , we have $L_i' = h_{i,D}(L_i)$. Hence $\{\omega_{ij}'\}$ gives the same element of $H^1(M, \mathcal{M}^1_D)$. Therefore we can define the map $dR_D: H^0_D(M, \mathcal{M}^2_D) \rightarrow H^1(M, \mathcal{M}^1_D)$. If $\{g_{ij}\} \in C^1_a(\mathfrak{U}, G_d)$ and $\{\omega_{ij}\} = \{\rho_D(g_{ij})\}$ is in $Z^1(\mathfrak{U}, \mathcal{M}^1_D)$, by the same calculation as in the proof of Proposition 1, we get $\omega_{ki}^g{}_{ij}{}^g{}_{jk}{}^g{}_{ki} = \omega_{ki}$. Hence we have

$$\omega_{ij} = L_j - L_i^g{}_{ij}, \quad L_i = \sum_{U_k \cap \bar{U}_i \neq \emptyset} e_k \omega_{ki}.$$

Therefore $\{L_i\}$ represents an element of $H^0_d(M, (\mathcal{D}_{E \otimes H}^{k-1}))$ and we have $dR(\{L_i\}) = \langle \omega \rangle$. Hence we have Theorem.

Note 1. If $\xi = \{g_{ij}\}$ is a G -bundle, then above decomposition of ω_{ij} gives a connection of D with respect to ξ (cf. [1], [2], [5], [6]).

Note 2. If $D = \bar{d}$, denote $\mathfrak{g}^{1,0}$ and $\mathfrak{g}^{0,1}$ the sheaves of germs of smooth matrix valued (1, 0)- and (0, 1)-type forms, we have the following commutative diagram with exact lines and columns

$$\begin{array}{ccccccc}
 & & 0 & & 0 & & 0 \\
 & & \uparrow & & \uparrow & & \uparrow \\
 0 & \longrightarrow & \mathcal{M}^{1,\bar{d}} & \longrightarrow & \mathfrak{g}^{0,1} & \xrightarrow{\bar{d}^e} & \mathcal{M}^{2,\bar{d}} \longrightarrow 0 \\
 & & \uparrow & & \uparrow & & \uparrow \\
 0 & \longrightarrow & \mathcal{M}^1 & \longrightarrow & \mathfrak{g}^1 & \xrightarrow{d^e} & \mathcal{M}^2 \longrightarrow 0 \\
 & & \uparrow & & \uparrow & & \uparrow \\
 0 & \longrightarrow & \mathcal{M}^{1,0} = \mathcal{M}^{1,\omega} & \longrightarrow & \mathfrak{g}^{1,0} & \xrightarrow{d^e} & \mathcal{M}^2 \longrightarrow 0 \\
 & & \uparrow & & \uparrow & & \uparrow \\
 & & 0 & & 0 & & 0
 \end{array}$$

Hence $\langle \omega \rangle \in H^1(M, \mathcal{M}^1)$ is in i^* -image if and only if there exists $\Theta \in Z^0_d(M, \mathcal{M}^2)$ such that $\iota dR(\Theta) = \langle \omega \rangle$ and $\pi^{0,2}\Theta = 0$ (cf. [18]).

16. We assume $C_{c(D)}$ admits the following resolution (cf. [6])

$$0 \longrightarrow C_{c(D)} \xrightarrow{i} C_d \xrightarrow{d^D} C^{1,D} \xrightarrow{d^D} C^{2,D} \longrightarrow \dots$$

We define the map $j: \mathcal{M}^1_D \rightarrow \mathcal{M}^1_{dD}$ by $j(\rho_D(g)) = \rho_{dD}(g)$. Then j is bijection and therefore induces a bijection $j^*: H^1(M, \mathcal{M}^1_D) \rightarrow H^1(M, \mathcal{M}^1_{dD})$. By the definition of \mathcal{M}^1_{dD} , $\Theta = \{\Theta_i\} \in Z^0_d(U, \mathcal{M}^2_{dD})$ is regarded to be $\Theta_i \in H^0(U_i, C^{2,D} \otimes \mathfrak{g})$. Hence we may consider $tr(\Theta_{\wedge \dots \wedge}^p \Theta)$ to be a d^D -closed $2p$ -form on M . The d^D -cohomology class of $tr(\Theta_{\wedge \dots \wedge}^p \Theta)$ is determined by $\iota dR_{dD}(\Theta) \in H^1(M, \mathcal{M}^1_{dD})$. Since dR_D is onto, we can define the p -th D -Chern class $c^p_D(\langle \omega \rangle)$ and the p -th D -Chern character $ch^p_D(\langle \omega \rangle)$ by

$$c^p_D(\langle \omega \rangle) = \text{the class of } c^p_D \in H^{2p}(M, C_{c(D)}),$$

$$ch^p_D(\langle \omega \rangle) = \text{the class of } \left(\frac{\sqrt{-1}}{2\pi}\right)^p \frac{1}{p!} tr(\Theta_{\wedge \dots \wedge}^p \Theta) \in H^{2p}(M, C_{c(D)}).$$

Here, we set $det(\mathbf{I} + (2\pi/\sqrt{-1})) = \mathbf{I} + c^1_D t + \dots + c^p_D t^p + \dots + c^n_D t^n$. Then, denoting $i_D: \mathbf{Z} \rightarrow C_{c(D)}$ the inclusion, we have

$$(26)_D \quad c^p_D(\rho_D^*(\xi)) = i_D^*(c^p(\xi)),$$

$$(26)'_D \quad ch^p_D(\rho_D^*(\xi)) = i_D^*(ch^p(\xi)).$$

In [6], the right hand side of (26)_D was called the p -th $c(D)$ -characteristic class of $\xi \in H^1(M, G_d)$.

Example. If M is a compact Kaehler manifold and $D = \bar{\partial}$, $c^p_{\bar{\partial}}(\langle \omega \rangle)$ is a $(0, 2p)$ -type class. If $\langle \omega \rangle = \rho_D^*(\xi)$, $c^p_{\bar{\partial}}(\langle \omega \rangle)$ is the $(0, 2p)$ -type part of $c^p(\xi)$, the p -th Chern class of ξ .

By definition and $(26)_{D'}$ we have

Proposition 3D. *Let $\langle \omega \rangle$ be an element of $H^1(M, \mathcal{A}^1_D)$. Then $\langle \omega \rangle$ can not be in ρ_D^* -image if $c^p_D(\langle \omega \rangle)$ is not an integral class for some p .*

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