

## On Differential Geometry of a Closed Space Curve at the Points Deviding into $2n$ Parts of Equal Length

By Naoo SAKURA

*Department of Mathematics, Faculty of Liberal Arts and Science, Shinshu University.*

(Received Nov. 6, 1961)

Let us take a fixed closed space curve  $C$  having the constant length  $l$ , and we assume it is of class  $C^3$ . If we take an original point  $O$  on it, as any point  $P$  on it can be expressed by the arc-length  $S$  measured from  $O$  to  $P$ , every point  $P$  on  $C$  can be denoted by the symbol  $P(s)$ , where  $0 \leq s \leq l$ .

We shall consider the system  $\mathfrak{S}$  of the points  $P_i(s_i)$ ,  $i=1, 2$ , ordered along the curve  $C$ , dividing it into two parts of equal length. Let  $s_1$  be the arc-length of  $OP_1$ . We shall take a fixed rectangular coordinate system  $O-x^1x^2x^3$ , and if we denote the coordinates of the points  $P_i$  by  $(x_i^1, x_i^2, x_i^3)$ , all these coordinates are one-valued continuous functions of  $s$ . Therefore, the system  $\mathfrak{S} = \{P_i(s_i), i=1, 2\}$  is a function of  $s_i$ .

The curvatures  $\kappa_i$  of the curve  $C$  at the two points  $P_i(s_i)$  are represented by

$$\kappa_i = \sqrt{(x_i''^1)^2 + (x_i''^2)^2 + (x_i''^3)^2}, \quad i=1, 2,$$

where  $\kappa_1, \kappa_2$  are the curvatures of the curve  $C$  and  $\mathbf{x}_1'', \mathbf{x}_2''$  are principal normal vectors at the points  $P_1, P_2$  respectively; the symbol  $x_i''$  are denoted by

$$x_i'' = \frac{d^2 x_i}{ds^2}.$$

Now we put

$$f(s_1) = \sqrt{(x_1''^1)^2 + (x_1''^2)^2 + (x_1''^3)^2} - \sqrt{(x_2''^1)^2 + (x_2''^2)^2 + (x_2''^3)^2},$$

then  $f(s_1)$  is a one-valued continuous function of  $s_1$  (this function can be considered as a function of the system  $\mathfrak{S}$ ). If we replace  $s_1$  by  $s_2$  (i. e., take another system  $\mathfrak{S}' = \{P_i(s'_i)\}$ , with  $s'_1 = s_2$ ),

we have easily

$$f(s_2) = \sqrt{(x_2''^1)^2 + (x_2''^2)^2 + (x_2''^3)^2} - \sqrt{(x_1''^1)^2 + (x_1''^2)^2 + (x_1''^3)^2},$$

and

$$f(s_1) = -f(s_2).$$

Therefore, we have at least one such  $\xi$  as satisfies both  $f(\xi) = 0$  and  $s_1 < \xi < s_2$ .

This  $\xi$  renders the curvatures of the two points  $s = \xi$ ,  $s = \xi + \frac{l}{2}$  equal.

Hence, we have the following theorem.

**Theorem 1.** *Among the systems  $\mathfrak{S} = \{P_i, i=1, 2\}$ , ordered along the curve  $C$ , dividing*

a rectifiable fixed closed curve  $C$  which is of class  $C^3$ , into two parts of equal length, there exists at least one system that makes the two curvatures equal. Moreover, there exists at least one system  $\mathfrak{S}$  making the torsions equal.

The proof of the latter half of the theorem is as follows:

The torsions  $\tau_i$  of the curve  $C$  at the points  $P_i(s_i)$  are represented by

$$\tau_i = \frac{1}{\kappa_i^2} |x_i' x_i'' x_i'''|, \quad i=1, 2,$$

where derivatives with respect to arc-length  $s$  will be characterized by primes,

$$x_i' \equiv \frac{dx_i}{ds}, \quad x_i'' \equiv \frac{d^2x_i}{ds^2}, \quad x_i''' \equiv \frac{d^3x_i}{ds^3}.$$

If we put

$$g(s_1) = \frac{1}{\kappa_1^2} |x_1' x_1'' x_1'''| - \frac{1}{\kappa_2^2} |x_2' x_2'' x_2'''|,$$

$(s_1)$  is a one-valued continuous function. We replace  $s_1$  by  $s_2$  then

$$g(s_2) = \frac{1}{\kappa_2^2} |x_2' x_2'' x_2'''| - \frac{1}{\kappa_1^2} |x_1' x_1'' x_1'''|.$$

Obviously, we have  $g(s_1) = -g(s_2)$ .

Therefore, we can find at least one such  $\eta$  as satisfies both  $g(\eta) = 0$  and  $s_1 < \eta < s_2$ .

Hence, the torsions of the curve at the two points  $s = \eta$  and  $s = \eta + \frac{l}{2}$  are equal. Thus, the latter half of the above theorem has been demonstrated.

Now we shall consider on the circle of curvature and osculating sphere of the curve  $C$ . We denote the radius of the circle of curvature and osculating sphere at the point of the curve  $C$  by  $\rho$  and  $R$  respectively. Then, these are given as

$$\rho = \frac{1}{\kappa}, \quad R^2 = \rho^2 + \left( \frac{d\rho}{ds} \frac{1}{\tau} \right)^2.$$

The radius of the circle of curvature at the points which have equal curvatures is equal.

If now we put

$$h(s_1) = \left[ \rho_1^2 + \left( \frac{d\rho_1}{ds} \frac{1}{\tau_1} \right)^2 \right]^{\frac{1}{2}} - \left[ \rho_2^2 + \left( \frac{d\rho_2}{ds} \frac{1}{\tau_2} \right)^2 \right]^{\frac{1}{2}},$$

where  $\rho_1, \rho_2$  are the radius of curvature at the two points  $P_1, P_2$  in the curve respectively, and then replace  $s_1$  by  $s_2$ , we have the following theorem, as the result of the same processes as above.

**Theorem 2.** (A). Among the systems of points  $\mathfrak{S} = \{P_i(s_i), i = 1, 2\}$ , dividing  $C$  into two parts of equal length, there exists at least one system making the areas of the two circles of curvature equal.

(B). Among the systems of points  $\mathfrak{S} = \{P_i(s_i), i = 1, 2\}$ , dividing  $C$  into two parts of equal length, there exists at least one system making the volumes of the two osculating spheres equal.

We have hitherto stated on the case of the system  $\mathfrak{S} = \{P_i(s_i), i = 1, 2\}$ , we

shall consider on  $\mathfrak{X}=\{P_j(s_j), j=1, 2, 3, 4\}$ .

The curvatures  $\kappa_j$ , ( $j=1, 2, 3, 4$ ) of the curve  $C$  at the four points  $P_j(s_j)$  are represented by

$$\kappa_j = \sqrt{(\mathbf{x}_j'' \mathbf{x}_j'')}, \quad (j=1, 2, 3, 4).$$

The function

$$\sqrt{(\mathbf{x}_1'' \mathbf{x}_1'')} - \sqrt{(\mathbf{x}_2'' \mathbf{x}_2'')} + \sqrt{(\mathbf{x}_3'' \mathbf{x}_3'')} - \sqrt{(\mathbf{x}_4'' \mathbf{x}_4'')}$$

can be considered as a function of the system  $\mathfrak{X}$  which is a one-valued continuous function of  $s_1$ .

We put

$$\varphi(s_1) = \sqrt{(\mathbf{x}_1'' \mathbf{x}_1'')} - \sqrt{(\mathbf{x}_2'' \mathbf{x}_2'')} + \sqrt{(\mathbf{x}_3'' \mathbf{x}_3'')} - \sqrt{(\mathbf{x}_4'' \mathbf{x}_4'')}$$

and if we replace  $s_1$  by  $s_2$ , we have easily  $\varphi(s_1) = -\varphi(s_2)$ .

Therefore, we have at least one such  $\xi$  as satisfies both  $\varphi(\xi) = 0$  and  $s_1 < \xi < s_2$ . This  $\xi$  renders the sum of the curvatures at the opposite two points  $P_1, P_3$  and that at the other opposite two points  $P_2, P_4$  equal.

As for the torsion, we put

$$\psi(s_1) = \frac{1}{\kappa_1^2} |\mathbf{x}_1' \mathbf{x}_1'' \mathbf{x}_1'''| - \frac{1}{\kappa_2^2} |\mathbf{x}_2' \mathbf{x}_2'' \mathbf{x}_2'''| + \frac{1}{\kappa_3^2} |\mathbf{x}_3' \mathbf{x}_3'' \mathbf{x}_3'''| - \frac{1}{\kappa_4^2} |\mathbf{x}_4' \mathbf{x}_4'' \mathbf{x}_4'''|,$$

by the same considerations on the function  $\psi(s_1)$ , we may have the similar result.

In the case of the division of the space curve  $C$  with all the properties abovesaid into  $2n$  parts of equal length, we can generally follow the same processes and have the same results.

### References

- (1) BLASCHKE, W. (1924) Vorlesungen über Differential Geometrie: I.
- (2) KUBOTA, T. (1935) Differential Geometry. IWANAMISHOTEN, TOKYO, (in Japanese).
- (3) EISENHART, L. p. (1940) An Introduction to Differential Geometry with use of the tensor calculus.
- (4) YANO, K. (1949) Differential Geometry. ASAKURASHOTEN, TOKYO, (in Japanese).
- (5) SASAKI, S. (1956) Differential Geometry. KYORITSU SYUPPAN, TOKYO, (in Japanese).
- (6) SAKURA, N. (1958) On some properties of a closed space curve divided into special Numbers of parts of equal length, *Journal of the faculty of liberal arts and science Shinshu University, no. 9, Part II.*
- (7) ERWIN, K. (1959) Differential Geometry.
- (8) ŌTSUKI, T. (1961) Differential Geometry, ASAKURASHOTEN, TOKYO, (in Japanese).